



# Geometrically-induced singularities in functionally graded magneto-electro-elastic wedges



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## ABSTRACT

Asymptotic solutions are proposed for geometrically-induced magneto-electro-elastic (MEE) singularities at the vertex of a rectilinearly polarized wedge that is made of functionally graded magneto-electro-elastic (FGMEE) materials. The material properties are assumed to vary along the thickness of the wedge, and the direction of polarization may not be parallel or perpendicular to the thickness direction. An eigenfunction expansion approach with the power series solution technique and domain decomposition is adopted to establish the asymptotic solutions by directly solving the three-dimensional equations of motion and Maxwell's equations in terms of mechanical displacement components and electric and magnetic potentials. Since the direction of polarization can be arbitrary in space, the in-plane components of displacement, electric and magnetic fields are generally coupled with the out-of-plane components. The solutions are presented here for the first time. The correctness of the proposed solutions is confirmed by comparing the orders of MEE singularities with the published results for wedges under anti-plane deformation and in-plane electric and magnetic fields. The proposed solutions are further employed to investigate the effects of the direction of polarization, vertex angle, boundary conditions and material-property gradient index on the MEE singularities in BaTiO<sub>3</sub>-CoFe<sub>2</sub>O<sub>4</sub> wedges.

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## 1. Introduction

Magneto-electro-elastic (MEE) materials exhibit mechanical-electric-magnetic coupling effects and have a wide range of applications in engineering structures, while functionally graded materials (FGMs) have the special feature of graded spatial compositions, which affords freedom in the design and manufacturing of novel structures. It is interesting and important to investigate geometrically-induced magneto-electro-elastic singularities in wedges made of functionally graded magneto-electro-elastic (FGMEE) materials because such singularities normally initiate cracking and worsen the functioning of structures.

Numerous studies of geometrically-induced stress singularities in elastic wedges have been conducted, and most of them were reviewed by Sinclair [1]. Williams [2,3] was at the forefront of investigating stress singularities at the vertex of an elastic wedge under extension or bending. Following his work, various investigations have been carried out on elastic wedges that are made of single and multiple materials, drawing on plane elasticity theory [4–12], plate theories [13–16], and three-dimensional elasticity

theory [17,18]. Huang and Chang [19,20] examined geometrically-induced stress singularities in FGM plates using classical plate theory and third-order shear deformation theory.

A few studies of geometrically-induced electroelastic singularities in piezoelectric wedges have been performed, and most of them make the plane strain assumption or the generalized plane deformation assumption. Using the plane strain assumption, Xu and Rajapakse [21] employed Lekhnitskii's complex potential functions to examine the in-plane electroelastic singularities at the vertex of a piezoelectric wedge, while Shang and Kitamura [22] utilized a modified version of the general solution of Wang and Zheng [23]. Hwu and Ikeda [24] made the generalized plane strain assumption and proposed an extended Stroh formulation to investigate the in-plane and out-of-plane electroelastic singularities in wedges. Chu et al. [25–27] adopted the generalized plane deformation assumption and conducted a series of analytical studies of geometrically-induced electroelastic singularities. Scherzer and Kuna [28], Chen et al. [29] and Chen and Ping [30] presented finite element solutions for in-plane singular electroelastic states at the vertex of a wedge. Based on the three-dimensional piezoelectricity theory, Huang and Hu [31] proposed asymptotic solutions at the vertex of a wedge.

Several studies have addressed magneto-electro-elastic singularities in MEE wedges and all of them considered wedges under

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anti-plane deformation and in-plane electric and magnetic fields and assumed that all of the physical quantities are independent of the coordinates along the thickness. Liu and Chue [32] applied the Mellin transform to analyze the singularities at the vertex of a bi-material MEE wedge, while Sue et al. [33] employed the complex potential function with an eigenfunction expansion method. Liu [34] extended the solution of Liu and Chue [32] to examine the magneto-electro-elastic singularities at the apex of an MEE wedge-junction structure, accounting for the air effect.

A review of the literature reveals a complete lack of investigation of geometrically-induced magneto-electro-elastic singularities in MEE wedges and FGMEE wedges based on the three-dimensional magneto-electro-elasticity theory. Accordingly, this paper aims to derive a three-dimensional asymptotic solution for the MEE singularities at the vertex of an FGMEE wedge with an arbitrary direction of polarization by extending the solutions of Huang and Hu [31] for a piezoelectric wedge. The eigenfunction expansion method is combined with the power series technique and a domain decomposition scheme to solve the three-dimensional equations of motion and Maxwell's equations in terms of mechanical displacement components, electric potential and magnetic potential in a cylindrical coordinate system. The correctness of the proposed solution is confirmed by comparison with the published results of Liu and Chue [32] for MEE wedges under anti-plane deformation and in-plane electric and magnetic fields. The proposed solutions are further applied to determine the orders of the MEE singularities in BaTiO<sub>3</sub>-CoFe<sub>2</sub>O<sub>4</sub> wedges whose material properties may vary along the thickness. The results demonstrate the influence of the orientation of polarization, vertex angle, material-property gradient index and boundary conditions on the orders of MEE singularities in a wedge.

## 2. Basic equations of 3D magneto-electro-elasticity

Consider an FGMEE wedge with vertex angle  $\beta$ , shown in Fig. 1, where the  $\bar{x}$ - $\bar{y}$ - $\bar{z}$  coordinate system is used to describe the material anisotropy, and the  $x$ - $y$ - $z$  coordinate system is used to describe the geometry of the wedge. The FGMEE material is

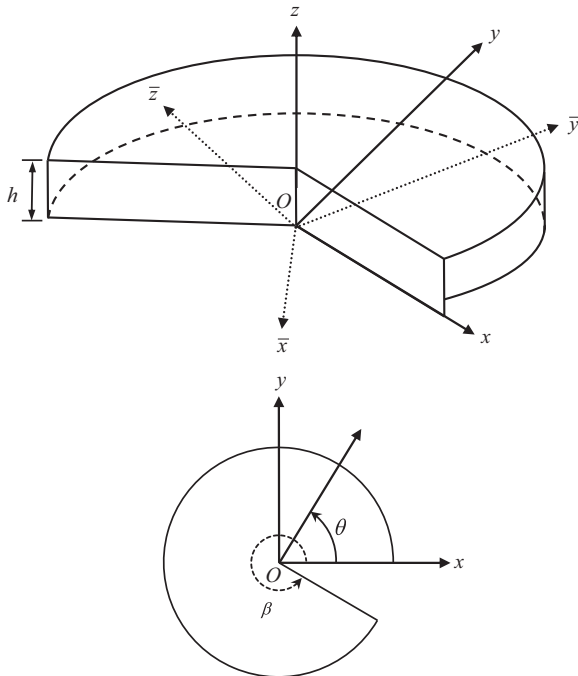


Fig. 1. Coordinate systems for a wedge.

assumed to be a transversely isotropic material with the polarization direction along the  $\bar{z}$  axis. The material properties are assumed to vary along the  $z$  axis. The  $\bar{x}$ - $\bar{y}$ - $\bar{z}$  coordinate system is not generally coincident with the  $x$ - $y$ - $z$  coordinate system, so the in-plane and out-of-plane physical quantities (mechanical displacement, electric and magnetic fields) are generally coupled.

The linear constitutive equations for the FGMEE material in the  $\bar{x}$ - $\bar{y}$ - $\bar{z}$  coordinate are given by

$$\{\bar{\sigma}\} = [\bar{c}]\{\bar{\varepsilon}\} - [\bar{e}]^T\{\bar{E}\} - [\bar{d}]^T\{\bar{H}\}, \quad (1a)$$

$$\{\bar{D}\} = [\bar{e}]\{\bar{\varepsilon}\} + [\bar{\eta}]\{\bar{E}\} + [\bar{g}]\{\bar{H}\}, \quad (1b)$$

$$\{\bar{B}\} = [\bar{d}]\{\bar{\varepsilon}\} + [\bar{g}]\{\bar{E}\} + [\bar{\mu}]\{\bar{H}\}, \quad (1c)$$

where  $\{\bar{\sigma}\} = \{\sigma_{\bar{x}\bar{x}} \ \sigma_{\bar{y}\bar{y}} \ \sigma_{\bar{z}\bar{z}} \ \sigma_{\bar{y}\bar{z}} \ \sigma_{\bar{z}\bar{x}} \ \sigma_{\bar{x}\bar{y}}\}^T$  and  $\{\bar{\varepsilon}\} = \{\varepsilon_{\bar{x}\bar{x}} \ \varepsilon_{\bar{y}\bar{y}} \ \varepsilon_{\bar{z}\bar{z}} \ 2\varepsilon_{\bar{y}\bar{z}} \ 2\varepsilon_{\bar{z}\bar{x}} \ 2\varepsilon_{\bar{x}\bar{y}}\}^T$  are the stress and strain vectors, respectively;  $\{\bar{D}\} = \{D_{\bar{x}} \ D_{\bar{y}} \ D_{\bar{z}}\}^T$  and  $\{\bar{B}\} = \{B_{\bar{x}} \ B_{\bar{y}} \ B_{\bar{z}}\}^T$  are the electric displacement and magnetic flux vectors, respectively;  $\{\bar{E}\} = \{E_{\bar{x}} \ E_{\bar{y}} \ E_{\bar{z}}\}^T$  and  $\{\bar{H}\} = \{H_{\bar{x}} \ H_{\bar{y}} \ H_{\bar{z}}\}^T$  are the vectors of the electric and magnetic fields, respectively.

$$[\bar{c}] = \begin{bmatrix} \bar{c}_{11} & \bar{c}_{12} & \bar{c}_{13} & 0 & 0 & 0 \\ \bar{c}_{12} & \bar{c}_{11} & \bar{c}_{13} & 0 & 0 & 0 \\ \bar{c}_{13} & \bar{c}_{13} & \bar{c}_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & \bar{c}_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & \bar{c}_{44} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{\bar{c}_{11} - \bar{c}_{12}}{2} \end{bmatrix},$$

$$[\bar{e}] = \begin{bmatrix} 0 & 0 & 0 & 0 & \bar{e}_{15} & 0 \\ 0 & 0 & 0 & \bar{e}_{15} & 0 & 0 \\ \bar{e}_{31} & \bar{e}_{31} & \bar{e}_{33} & 0 & 0 & 0 \end{bmatrix}$$

$$[\bar{d}] = \begin{bmatrix} 0 & 0 & 0 & 0 & \bar{d}_{15} & 0 \\ 0 & 0 & 0 & \bar{d}_{15} & 0 & 0 \\ \bar{d}_{31} & \bar{d}_{31} & \bar{d}_{33} & 0 & 0 & 0 \end{bmatrix},$$

$$[\bar{\eta}] = \begin{bmatrix} \bar{\eta}_{11} & 0 & 0 \\ 0 & \bar{\eta}_{11} & 0 \\ 0 & 0 & \bar{\eta}_{33} \end{bmatrix}, \quad [\bar{\mu}] = \begin{bmatrix} \bar{\mu}_{11} & 0 & 0 \\ 0 & \bar{\mu}_{11} & 0 \\ 0 & 0 & \bar{\mu}_{33} \end{bmatrix},$$

$$[\bar{g}] = \begin{bmatrix} \bar{g}_{11} & 0 & 0 \\ 0 & \bar{g}_{11} & 0 \\ 0 & 0 & \bar{g}_{33} \end{bmatrix}. \quad (2)$$

where  $[\bar{c}]$ ,  $[\bar{e}]$ ,  $[\bar{d}]$ ,  $[\bar{\eta}]$ ,  $[\bar{\mu}]$  and  $[\bar{g}]$  are the elastic stiffness constant, piezoelectric coefficient, piezomagnetic coefficient, dielectric constant, magnetic permeability, and magnetoelastic coefficient matrices, respectively, and all of these are functions of  $z$ .

The cylindrical coordinate system  $(r, \theta, z)$  (Fig. 1) is used to investigate the MEE singularities as  $r$  approaches zero in the wedge. Hence, Eqs. (1) and (2) have to be transformed to  $(r, \theta, z)$  from  $(\bar{x}, \bar{y}, \bar{z})$  and rewritten as

$$\{\sigma\} = [c]\{\varepsilon\} - [e]^T\{E\} - [d]^T\{H\}, \quad (3a)$$

$$\{D\} = [e]\{\varepsilon\} + [\eta]\{E\} + [g]\{H\}, \quad (3b)$$

$$\{B\} = [d]\{\varepsilon\} + [g]\{E\} + [\mu]\{H\}, \quad (3c)$$

where

$$[c] = \begin{bmatrix} c_{11} & c_{12} & c_{13} & c_{14} & c_{15} & c_{16} \\ c_{12} & c_{22} & c_{23} & c_{24} & c_{25} & c_{26} \\ c_{13} & c_{23} & c_{33} & c_{34} & c_{35} & c_{36} \\ c_{14} & c_{24} & c_{34} & c_{44} & c_{45} & c_{46} \\ c_{15} & c_{25} & c_{35} & c_{45} & c_{55} & c_{56} \\ c_{16} & c_{26} & c_{36} & c_{46} & c_{56} & c_{66} \end{bmatrix},$$

$$[e] = \begin{bmatrix} e_{11} & e_{12} & e_{13} & e_{14} & e_{15} & e_{16} \\ e_{21} & e_{22} & e_{23} & e_{24} & e_{25} & e_{26} \\ e_{31} & e_{32} & e_{33} & e_{34} & e_{35} & e_{36} \end{bmatrix}$$

$$[d] = \begin{bmatrix} d_{11} & d_{12} & d_{13} & d_{14} & d_{15} & d_{16} \\ d_{21} & d_{22} & d_{23} & d_{24} & d_{25} & d_{26} \\ d_{31} & d_{32} & d_{33} & d_{34} & d_{35} & d_{36} \end{bmatrix},$$

$$[\eta] = \begin{bmatrix} \eta_{11} & \eta_{12} & \eta_{13} \\ \eta_{12} & \eta_{22} & \eta_{23} \\ \eta_{13} & \eta_{23} & \eta_{33} \end{bmatrix}, \quad [\mu] = \begin{bmatrix} \mu_{11} & \mu_{12} & \mu_{13} \\ \mu_{12} & \mu_{22} & \mu_{23} \\ \mu_{13} & \mu_{23} & \mu_{33} \end{bmatrix},$$

$$[g] = \begin{bmatrix} g_{11} & g_{12} & g_{13} \\ g_{12} & g_{22} & g_{23} \\ g_{13} & g_{23} & g_{33} \end{bmatrix}.$$

Now the material properties matrices  $[c]$ ,  $[e]$ ,  $[d]$ ,  $[\eta]$ ,  $[\mu]$  and  $[g]$  are related to  $[\bar{c}]$ ,  $[\bar{e}]$ ,  $[\bar{d}]$ ,  $[\bar{\eta}]$ ,  $[\bar{\mu}]$  and  $[\bar{g}]$ , respectively, and are the functions of  $\theta$ ,  $z$  and the angles between the axes of  $\bar{x}$ - $\bar{y}$ - $\bar{z}$  and  $x$ - $y$ - $z$ . These relations are specified in Appendix A.

To develop the asymptotic solutions to examine the geometrically-induced magneto-electro-elastic singularities as  $r$  approaches zero in a wedge, the body forces, free electric charges and magnetic charges are ignored, and the equations of motion and Maxwell's equations are

$$\frac{\partial \sigma_{rr}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{r\theta}}{\partial \theta} + \frac{\partial \sigma_{rz}}{\partial z} + \frac{(\sigma_{rr} - \sigma_{\theta\theta})}{r} = \rho^* \frac{\partial^2 u_r^*}{\partial t^2}, \tag{4a}$$

$$\frac{\partial \sigma_{r\theta}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{\theta\theta}}{\partial \theta} + \frac{\partial \sigma_{\theta z}}{\partial z} + 2 \frac{\sigma_{r\theta}}{r} = \rho^* \frac{\partial^2 u_\theta^*}{\partial t^2}, \tag{4b}$$

$$\frac{\partial \sigma_{rz}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{\theta z}}{\partial \theta} + \frac{\partial \sigma_{zz}}{\partial z} + \frac{\sigma_{rz}}{r} = \rho^* \frac{\partial^2 u_z^*}{\partial t^2}, \tag{4c}$$

$$\frac{1}{r} \frac{\partial (rD_r)}{\partial r} + \frac{1}{r} \frac{\partial D_\theta}{\partial \theta} + \frac{\partial D_z}{\partial z} = 0, \tag{4d}$$

$$\frac{1}{r} \frac{\partial (rB_r)}{\partial r} + \frac{1}{r} \frac{\partial B_\theta}{\partial \theta} + \frac{\partial B_z}{\partial z} = 0, \tag{4e}$$

where  $\rho^*$  is the density of the material, and  $u_i^*$  ( $i = r, \theta, z$ ) is the displacement component in the  $i$  direction.

Using electric field-electric potential and magnetic field-magnetic potential relations,

$$\begin{aligned} E_r &= -\frac{\partial \phi^*}{\partial r}, \quad E_\theta = -\frac{1}{r} \frac{\partial \phi^*}{\partial \theta}, \quad E_z = -\frac{\partial \phi^*}{\partial z}, \\ H_r &= -\frac{\partial \psi^*}{\partial r}, \quad H_\theta = -\frac{1}{r} \frac{\partial \psi^*}{\partial \theta} \quad \text{and} \quad H_z = -\frac{\partial \psi^*}{\partial z}, \end{aligned} \tag{5}$$

as well as the strain-displacement relations, Eqs. (4a)–(4e) can be expressed in terms of mechanical displacement components ( $u_r^*$ ,  $u_\theta^*$  and  $u_z^*$ ), electric potential ( $\phi^*$ ) and magnetic potential ( $\psi^*$ ) as follows:

$$\begin{aligned} &\left[ c_{11} \frac{\partial^2}{\partial r^2} + \left( \frac{c_{66}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + c_{55} \frac{\partial^2}{\partial z^2} + \left( \frac{2c_{16}}{r} \right) \frac{\partial^2}{\partial r \partial \theta} \right. \\ &\quad \left. + 2c_{15} \frac{\partial^2}{\partial r \partial z} + \left( \frac{2c_{56}}{r} \right) \frac{\partial^2}{\partial \theta \partial z} + \left( c_{11} + \frac{\partial c_{16}}{\partial \theta} + r \frac{\partial c_{15}}{\partial z} \right) \frac{\partial}{\partial r} \right] \end{aligned}$$

$$\begin{aligned} &+ \left( \frac{\partial c_{66}}{\partial \theta} + r \frac{\partial c_{56}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} + \left( c_{15} + \frac{\partial c_{56}}{\partial \theta} + r \frac{\partial c_{55}}{\partial z} \right) \frac{\partial}{r \partial z} \\ &+ \left( -c_{22} + \frac{\partial c_{26}}{\partial \theta} + r \frac{\partial c_{25}}{\partial z} \right) \frac{1}{r^2} - \rho^* \frac{\partial^2}{\partial t^2} \Big] u_r^* \\ &+ \left[ c_{16} \frac{\partial^2}{\partial r^2} + \left( \frac{c_{26}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + c_{45} \frac{\partial^2}{\partial z^2} + (c_{12} + c_{66}) \frac{\partial^2}{r \partial r \partial \theta} \right. \\ &\quad \left. + (c_{14} + c_{56}) \frac{\partial^2}{\partial r \partial z} + (c_{25} + c_{46}) \frac{\partial^2}{r \partial \theta \partial z} \right. \\ &\quad \left. + \left( -c_{26} + \frac{\partial c_{66}}{\partial \theta} + r \frac{\partial c_{56}}{\partial z} \right) \frac{\partial}{r \partial r} \right. \\ &\quad \left. + \left( -c_{22} - c_{66} + \frac{\partial c_{26}}{\partial \theta} + r \frac{\partial c_{25}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} \right. \\ &\quad \left. + \left( c_{14} - c_{24} - c_{56} + \frac{\partial c_{46}}{\partial \theta} + r \frac{\partial c_{45}}{\partial z} \right) \right. \\ &\quad \left. \times \frac{\partial}{r \partial z} + \left( c_{26} - \frac{\partial c_{66}}{\partial \theta} - \frac{\partial c_{56}}{\partial z} \right) \frac{1}{r^2} \right] u_\theta^* \\ &+ \left[ c_{15} \frac{\partial^2}{\partial r^2} + \left( \frac{c_{46}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + c_{35} \frac{\partial^2}{\partial z^2} + (c_{14} + c_{56}) \frac{\partial^2}{r \partial r \partial \theta} + (c_{13} + c_{55}) \right. \\ &\quad \left. \times \frac{\partial^2}{\partial r \partial z} + (c_{36} + c_{45}) \frac{\partial^2}{r \partial \theta \partial z} + \left( c_{15} - c_{25} + \frac{\partial c_{56}}{\partial \theta} + r \frac{\partial c_{55}}{\partial z} \right) \frac{\partial}{r \partial r} \right. \\ &\quad \left. + \left( -c_{24} + \frac{\partial c_{46}}{\partial \theta} + r \frac{\partial c_{45}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} \right. \\ &\quad \left. + \left( c_{13} - c_{23} + \frac{\partial c_{36}}{\partial \theta} + r \frac{\partial c_{35}}{\partial z} \right) \frac{\partial}{r \partial z} \right] u_z^* \\ &+ \left[ e_{11} \frac{\partial^2}{\partial r^2} + \left( \frac{e_{26}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + e_{35} \frac{\partial^2}{\partial z^2} + (e_{16} + e_{21}) \frac{\partial^2}{r \partial r \partial \theta} \right. \\ &\quad \left. + (e_{15} + e_{31}) \frac{\partial^2}{\partial r \partial z} + (e_{25} + e_{36}) \frac{\partial^2}{r \partial \theta \partial z} \right. \\ &\quad \left. + \left( e_{11} - e_{12} + \frac{\partial e_{16}}{\partial \theta} + r \frac{\partial e_{15}}{\partial z} \right) \frac{\partial}{r \partial r} + \left( -e_{22} + \frac{\partial e_{26}}{\partial \theta} + r \frac{\partial e_{25}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} \right. \\ &\quad \left. + \left( e_{31} - e_{32} + \frac{\partial e_{36}}{\partial \theta} + r \frac{\partial e_{35}}{\partial z} \right) \frac{\partial}{r \partial z} \right] \phi^* \\ &+ \left[ d_{11} \frac{\partial^2}{\partial r^2} + \left( \frac{d_{26}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + d_{35} \frac{\partial^2}{\partial z^2} + (d_{16} + d_{21}) \frac{\partial^2}{r \partial r \partial \theta} \right. \\ &\quad \left. + (d_{15} + d_{31}) \frac{\partial^2}{\partial r \partial z} + (d_{25} + d_{36}) \frac{\partial^2}{r \partial \theta \partial z} \right. \\ &\quad \left. + \left( d_{11} - d_{12} + \frac{\partial d_{16}}{\partial \theta} + r \frac{\partial d_{15}}{\partial z} \right) \frac{\partial}{r \partial r} + \left( -d_{22} + \frac{\partial d_{26}}{\partial \theta} + r \frac{\partial d_{16}}{\partial z} \right) \right. \\ &\quad \left. \times \frac{\partial}{r^2 \partial \theta} + \left( d_{31} - d_{32} + \frac{\partial d_{36}}{\partial \theta} + r \frac{\partial d_{35}}{\partial z} \right) \frac{\partial}{r \partial z} \right] \psi^* = 0, \tag{6a} \end{aligned}$$

$$\begin{aligned} &\left[ c_{16} \frac{\partial^2}{\partial r^2} + \left( \frac{c_{26}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + c_{45} \frac{\partial^2}{\partial z^2} + (c_{12} + c_{66}) \frac{\partial^2}{r \partial r \partial \theta} \right. \\ &\quad \left. + (c_{14} + c_{56}) \frac{\partial^2}{\partial r \partial z} + (c_{25} + c_{46}) \frac{\partial^2}{r \partial \theta \partial z} + \left( 2c_{16} + c_{26} + \frac{\partial c_{12}}{\partial \theta} + r \frac{\partial c_{14}}{\partial z} \right) \frac{\partial}{r \partial r} \right. \\ &\quad \left. + \left( c_{22} + c_{66} + \frac{\partial c_{26}}{\partial \theta} + r \frac{\partial c_{46}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} + \left( c_{24} + 2c_{56} + \frac{\partial c_{25}}{\partial \theta} + r \frac{\partial c_{45}}{\partial z} \right) \right. \\ &\quad \left. \times \frac{\partial}{r \partial z} + \left( c_{26} + \frac{\partial c_{22}}{\partial \theta} + r \frac{\partial c_{24}}{\partial z} \right) \frac{1}{r^2} \right] u_r^* + \left[ c_{66} \frac{\partial^2}{\partial r^2} + \left( \frac{c_{22}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + c_{44} \frac{\partial^2}{\partial z^2} \right. \\ &\quad \left. + \left( \frac{2c_{26}}{r} \right) \frac{\partial^2}{\partial r \partial \theta} + 2c_{46} \frac{\partial^2}{\partial r \partial z} + 2c_{24} \frac{\partial^2}{r \partial \theta \partial z} \right. \\ &\quad \left. + \left( c_{66} + \frac{\partial c_{26}}{\partial \theta} + r \frac{\partial c_{46}}{\partial z} \right) \frac{\partial}{r \partial r} + \left( \frac{\partial c_{22}}{\partial \theta} + r \frac{\partial c_{24}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} \right. \\ &\quad \left. + \left( c_{46} + \frac{\partial c_{24}}{\partial \theta} + r \frac{\partial c_{44}}{\partial z} \right) \frac{\partial}{r \partial z} + \left( -c_{66} - \frac{\partial c_{26}}{\partial \theta} - r \frac{\partial c_{46}}{\partial z} \right) \frac{1}{r^2} - \rho^* \frac{\partial^2}{\partial t^2} \right] u_\theta^* \\ &+ \left[ c_{56} \frac{\partial^2}{\partial r^2} + \left( \frac{c_{24}}{r^2} \right) \frac{\partial^2}{\partial \theta^2} + c_{34} \frac{\partial^2}{\partial z^2} + (c_{25} + c_{46}) \frac{\partial^2}{r \partial r \partial \theta} \right. \\ &\quad \left. + (c_{36} + c_{45}) \frac{\partial^2}{\partial r \partial z} + (c_{23} + c_{44}) \frac{\partial^2}{r \partial \theta \partial z} + \left( 2c_{56} + \frac{\partial c_{25}}{\partial \theta} + r \frac{\partial c_{45}}{\partial z} \right) \frac{\partial}{r \partial r} \right. \\ &\quad \left. + \left( c_{46} + \frac{\partial c_{24}}{\partial \theta} + r \frac{\partial c_{44}}{\partial z} \right) \frac{\partial}{r^2 \partial \theta} + \left( 2c_{36} + \frac{\partial c_{23}}{\partial \theta} + r \frac{\partial c_{34}}{\partial z} \right) \frac{\partial}{r \partial z} \right] u_z^* \end{aligned}$$



### 3. Construction of asymptotic solution

The eigenfunction expansion approach, which Hartranft and Sih [7] had used for 3D elastic wedges, is adopted herein. The mechanical displacements, electric potential and magnetic potential are expressed as

$$u_r^*(r, \theta, z, t) = \left[ \sum_{m=1}^{\infty} \sum_{n=0}^{\infty} r^{\lambda_m+n} \hat{U}_n^{(m)}(\theta, z) \right] e^{i\omega t}, \tag{7a}$$

$$u_\theta^*(r, \theta, z, t) = \left[ \sum_{m=1}^{\infty} \sum_{n=0}^{\infty} r^{\lambda_m+n} \hat{V}_n^{(m)}(\theta, z) \right] e^{i\omega t}, \tag{7b}$$

$$u_z^*(r, \theta, z, t) = \left[ \sum_{m=1}^{\infty} \sum_{n=0}^{\infty} r^{\lambda_m+n} \hat{W}_n^{(m)}(\theta, z) \right] e^{i\omega t}, \tag{7c}$$

$$\phi^*(r, \theta, z, t) = \left[ \sum_{m=1}^{\infty} \sum_{n=0}^{\infty} r^{\lambda_m+n} \hat{\Phi}_n^{(m)}(\theta, z) \right] e^{i\omega t}, \tag{7d}$$

$$\psi^*(r, \theta, z, t) = \left[ \sum_{m=1}^{\infty} \sum_{n=0}^{\infty} r^{\lambda_m+n} \hat{\Psi}_n^{(m)}(\theta, z) \right] e^{i\omega t}, \tag{7e}$$

The characteristic values  $\lambda_m$  may be real or complex for MEE wedges. For FGMEW wedges,  $\lambda_m$  is expected to depend on  $z$  because the material properties are functions of  $z$ . To ensure the finite displacements, electric field and magnetic field at  $r=0$ , the real part of  $\lambda_m$  is required to be positive. Notably, when the real part of  $\lambda_m$  ( $\text{Re}[\lambda_m]$ ) is less than unity, the order of the singularities of stress, electric displacement and magnetic flux is  $\text{Re}[\lambda_m] - 1$ .

Substituting Eqs. (7a)–(7e) into Eqs. (6a)–(6e), carefully rearranging and considering the terms with the lowest order of  $r$  yields,

$$\begin{aligned} & \frac{\partial^2 \hat{U}_0^{(m)}}{\partial \theta^2} + p_1 \frac{\partial \hat{U}_0^{(m)}}{\partial \theta} + p_2 \hat{U}_0^{(m)} + p_3 \frac{\partial^2 \hat{V}_0^{(m)}}{\partial \theta^2} + p_4 \frac{\partial \hat{V}_0^{(m)}}{\partial \theta} \\ & + p_5 \hat{V}_0^{(m)} + p_6 \frac{\partial^2 \hat{W}_0^{(m)}}{\partial \theta^2} + p_7 \frac{\partial \hat{W}_0^{(m)}}{\partial \theta} + p_8 \hat{W}_0^{(m)} \\ & + p_9 \frac{\partial^2 \hat{\Phi}_0^{(m)}}{\partial \theta^2} + p_{10} \frac{\partial \hat{\Phi}_0^{(m)}}{\partial \theta} + p_{11} \hat{\Phi}_0^{(m)} + p_{12} \frac{\partial^2 \hat{\Psi}_0^{(m)}}{\partial \theta^2} \\ & + p_{13} \frac{\partial \hat{\Psi}_0^{(m)}}{\partial \theta} + p_{14} \hat{\Psi}_0^{(m)} = 0, \end{aligned} \tag{8a}$$

$$\begin{aligned} & \frac{\partial^2 \hat{V}_0^{(m)}}{\partial \theta^2} + q_1 \frac{\partial \hat{V}_0^{(m)}}{\partial \theta} + q_2 \hat{V}_0^{(m)} + q_3 \frac{\partial^2 \hat{U}_0^{(m)}}{\partial \theta^2} + q_4 \frac{\partial \hat{U}_0^{(m)}}{\partial \theta} \\ & + q_5 \hat{U}_0^{(m)} + q_6 \frac{\partial^2 \hat{W}_0^{(m)}}{\partial \theta^2} + q_7 \frac{\partial \hat{W}_0^{(m)}}{\partial \theta} + q_8 \hat{W}_0^{(m)} \\ & + q_9 \frac{\partial^2 \hat{\Phi}_0^{(m)}}{\partial \theta^2} + q_{10} \frac{\partial \hat{\Phi}_0^{(m)}}{\partial \theta} + q_{11} \hat{\Phi}_0^{(m)} + q_{12} \frac{\partial^2 \hat{\Psi}_0^{(m)}}{\partial \theta^2} \\ & + q_{13} \frac{\partial \hat{\Psi}_0^{(m)}}{\partial \theta} + q_{14} \hat{\Psi}_0^{(m)} = 0, \end{aligned} \tag{8b}$$

$$\begin{aligned} & \frac{\partial^2 \hat{W}_0^{(m)}}{\partial \theta^2} + r_1 \frac{\partial \hat{W}_0^{(m)}}{\partial \theta} + r_2 \hat{W}_0^{(m)} + r_3 \frac{\partial^2 \hat{U}_0^{(m)}}{\partial \theta^2} + r_4 \frac{\partial \hat{U}_0^{(m)}}{\partial \theta} \\ & + r_5 \hat{U}_0^{(m)} + r_6 \frac{\partial^2 \hat{V}_0^{(m)}}{\partial \theta^2} + r_7 \frac{\partial \hat{V}_0^{(m)}}{\partial \theta} + r_8 \hat{V}_0^{(m)} \\ & + r_9 \frac{\partial^2 \hat{\Phi}_0^{(m)}}{\partial \theta^2} + r_{10} \frac{\partial \hat{\Phi}_0^{(m)}}{\partial \theta} + r_{11} \hat{\Phi}_0^{(m)} + r_{12} \frac{\partial^2 \hat{\Psi}_0^{(m)}}{\partial \theta^2} \\ & + r_{13} \frac{\partial \hat{\Psi}_0^{(m)}}{\partial \theta} + r_{14} \hat{\Psi}_0^{(m)} = 0, \end{aligned} \tag{8c}$$

$$\begin{aligned} & \frac{\partial^2 \hat{\Phi}_0^{(m)}}{\partial \theta^2} + s_1 \frac{\partial \hat{\Phi}_0^{(m)}}{\partial \theta} + s_2 \hat{\Phi}_0^{(m)} + s_3 \frac{\partial^2 \hat{U}_0^{(m)}}{\partial \theta^2} + s_4 \frac{\partial \hat{U}_0^{(m)}}{\partial \theta} \\ & + s_5 \hat{U}_0^{(m)} + s_6 \frac{\partial^2 \hat{V}_0^{(m)}}{\partial \theta^2} + s_7 \frac{\partial \hat{V}_0^{(m)}}{\partial \theta} + s_8 \hat{V}_0^{(m)} \end{aligned}$$

$$\begin{aligned} & + s_9 \frac{\partial^2 \hat{W}_0^{(m)}}{\partial \theta^2} + s_{10} \frac{\partial \hat{W}_0^{(m)}}{\partial \theta} + s_{11} \hat{W}_0^{(m)} + s_{12} \frac{\partial^2 \hat{\Psi}_0^{(m)}}{\partial \theta^2} \\ & + s_{13} \frac{\partial \hat{\Psi}_0^{(m)}}{\partial \theta} + s_{14} \hat{\Psi}_0^{(m)} = 0, \end{aligned} \tag{8d}$$

$$\begin{aligned} & \frac{\partial^2 \hat{\Psi}_0^{(m)}}{\partial \theta^2} + t_1 \frac{\partial \hat{\Psi}_0^{(m)}}{\partial \theta} + t_2 \hat{\Psi}_0^{(m)} + t_3 \frac{\partial^2 \hat{U}_0^{(m)}}{\partial \theta^2} + t_4 \frac{\partial \hat{U}_0^{(m)}}{\partial \theta} + t_5 \hat{U}_0^{(m)} \\ & + t_6 \frac{\partial^2 \hat{V}_0^{(m)}}{\partial \theta^2} + t_7 \frac{\partial \hat{V}_0^{(m)}}{\partial \theta} + t_8 \hat{V}_0^{(m)} + t_9 \frac{\partial^2 \hat{W}_0^{(m)}}{\partial \theta^2} + t_{10} \frac{\partial \hat{W}_0^{(m)}}{\partial \theta} \\ & + t_{11} \hat{W}_0^{(m)} + t_{12} \frac{\partial^2 \hat{\Phi}_0^{(m)}}{\partial \theta^2} + t_{13} \frac{\partial \hat{\Phi}_0^{(m)}}{\partial \theta} + t_{14} \hat{\Phi}_0^{(m)} = 0, \end{aligned} \tag{8e}$$

where  $p_i, q_i, r_i, s_i$  and  $t_i$  ( $i=1-14$ ) are functions of  $\theta$  and  $z$  and are defined in Appendix B. Careful examination of Eqs. (8a)–(8e) reveals that when  $\lambda_m$  at  $z=z_l$  is sought, the material properties at  $z=z_l$  must be used to determine  $p_i, q_i, r_i, s_i$  and  $t_i$ .

Eq. (8) represent a set of ordinary differential equations with variable coefficients. The three displacement components, electric potential and magnetic potential are generally coupled in Eqs. (8a)–(8e). The exact closed-form solutions to Eqs. (8a)–(8e) are intractable, if they exist. The power series method can be directly applied to establish a general solution to these ordinary differential equations. Very high-order terms are commonly needed to obtain an accurate solution and they typically cause numerical difficulties. To overcome these difficulties, a domain decomposition technique is applied in conjunction with the power series method to find a general solution to Eqs. (8a)–(8e).

The whole domain of  $\theta$  is divided into numerous sub-domains (Fig. 2). A series solution for each sub-domain is constructed directly using the traditional power series method. Then, a general solution over the whole  $\theta$  domain is obtained by assembling the solutions in all sub-domains and imposing continuity conditions between each pair of adjacent sub-domains. Notably, this solution procedure is also valid for a wedge that has different materials in different sub-domains of  $\theta$ .

To develop the series solution for sub-domain  $i$  where  $\theta_{i-1} \leq \theta \leq \theta_i$ , the variable coefficients at  $z=z_l$  in Eqs. (8a)–(8e) are expressed by Taylor's series with respect to the middle point of the sub-domain  $\bar{\theta}_i$ ,

$$p_j(\theta, z_l) = \sum_{k=0}^K (\chi_j^{(i)})_k (\theta - \bar{\theta}_i)^k, \quad q_j(\theta, z_l) = \sum_{k=0}^K (\kappa_j^{(i)})_k (\theta - \bar{\theta}_i)^k,$$

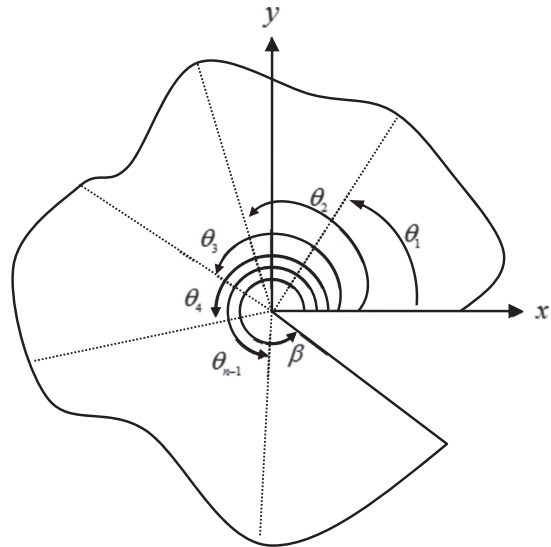


Fig. 2. Sub-domains for  $\theta \in [0, \beta]$

$$r_j(\theta, z_i) = \sum_{k=0}^K (\vartheta_j)_k^{(i)} (\theta - \bar{\theta}_i)^k, \quad s_j(\theta, z_i) = \sum_{k=0}^K (\xi_j)_k^{(i)} (\theta - \bar{\theta}_i)^k,$$

$$t_j(\theta, z_i) = \sum_{k=0}^K (\zeta_j)_k^{(i)} (\theta - \bar{\theta}_i)^k. \tag{9}$$

Similarly, the solutions to Eqs. (8a)–(8e) in the sub-domain are expressed as

$$\hat{U}_{0i}^{(m)} = \sum_{j=0}^J \hat{A}_j^{(i)} (\theta - \bar{\theta}_i)^j, \quad \hat{V}_{0i}^{(m)} = \sum_{j=0}^J \hat{B}_j^{(i)} (\theta - \bar{\theta}_i)^j,$$

$$\hat{W}_{0i}^{(m)} = \sum_{j=0}^J \hat{C}_j^{(i)} (\theta - \bar{\theta}_i)^j, \quad \hat{\Phi}_{0i}^{(m)} = \sum_{j=0}^J \hat{D}_j^{(i)} (\theta - \bar{\theta}_i)^j$$

$$\hat{\Psi}_{0i}^{(m)} = \sum_{j=0}^J \hat{E}_j^{(i)} (\theta - \bar{\theta}_i)^j. \tag{10}$$

Substituting Eqs. (9) and (10) into Eqs. (8a)–(8e) yields the following recurrence relations among the coefficients in Eq. (10):

$$\hat{A}_{j+2}^{(i)} + (\chi_3)_0^{(i)} \hat{B}_{j+2}^{(i)} + (\chi_6)_0^{(i)} \hat{C}_{j+2}^{(i)} + (\chi_9)_0^{(i)} \hat{D}_{j+2}^{(i)} + (\chi_{12})_0^{(i)} \hat{E}_{j+2}^{(i)}$$

$$= \frac{-1}{(j+2)(j+1)} \left\{ \sum_{k=0}^{j-1} \left[ (k+2)(k+1) \left( (\chi_3)_{j-k}^{(i)} \hat{B}_{k+2}^{(i)} + (\chi_6)_{j-k}^{(i)} \hat{C}_{k+2}^{(i)} \right. \right. \right.$$

$$\left. \left. + (\chi_9)_{j-k}^{(i)} \hat{D}_{k+2}^{(i)} + (\chi_{12})_{j-k}^{(i)} \hat{E}_{k+2}^{(i)} \right) \right.$$

$$\left. + \sum_{k=0}^j \left[ (k+1) \left( (\chi_1)_{j-k}^{(i)} \hat{A}_{k+1}^{(i)} + (\chi_4)_{j-k}^{(i)} \right. \right. \right.$$

$$\left. \left. \times \hat{B}_{k+1}^{(i)} + (\chi_7)_{j-k}^{(i)} \hat{C}_{k+1}^{(i)} + (\chi_{10})_{j-k}^{(i)} \hat{D}_{k+1}^{(i)} + (\chi_{13})_{j-k}^{(i)} \hat{E}_{k+1}^{(i)} \right) \right.$$

$$\left. + \left( (\chi_2)_{j-k}^{(i)} \hat{A}_k^{(i)} + (\chi_5)_{j-k}^{(i)} \hat{B}_k^{(i)} + (\chi_8)_{j-k}^{(i)} \hat{C}_k^{(i)} \right. \right.$$

$$\left. \left. + (\chi_{11})_{j-k}^{(i)} \hat{D}_k^{(i)} + (\chi_{14})_{j-k}^{(i)} \hat{E}_k^{(i)} \right) \right\}, \tag{11a}$$

$$\hat{B}_{j+2}^{(i)} + (\kappa_3)_0^{(i)} \hat{A}_{j+2}^{(i)} + (\kappa_6)_0^{(i)} \hat{C}_{j+2}^{(i)} + (\kappa_9)_0^{(i)} \hat{D}_{j+2}^{(i)} + (\kappa_{12})_0^{(i)} \hat{E}_{j+2}^{(i)}$$

$$= \frac{-1}{(j+2)(j+1)} \left\{ \sum_{k=0}^{j-1} \left[ (k+2)(k+1) \times \left( (\kappa_3)_{j-k}^{(i)} \hat{A}_{k+2}^{(i)} + (\kappa_6)_{j-k}^{(i)} \hat{C}_{k+2}^{(i)} \right. \right. \right.$$

$$\left. \left. + (\kappa_9)_{j-k}^{(i)} \hat{D}_{k+2}^{(i)} + (\kappa_{12})_{j-k}^{(i)} \hat{E}_{k+2}^{(i)} \right) \right] + \sum_{k=0}^j \left[ (k+1) \left( (\kappa_1)_{j-k}^{(i)} \hat{B}_{k+1}^{(i)} \right. \right.$$

$$\left. \left. + (\kappa_4)_{j-k}^{(i)} \times \hat{A}_{k+1}^{(i)} + (\kappa_7)_{j-k}^{(i)} \hat{C}_{k+1}^{(i)} + (\kappa_{10})_{j-k}^{(i)} \hat{D}_{k+1}^{(i)} + (\kappa_{13})_{j-k}^{(i)} \hat{E}_{k+1}^{(i)} \right) \right.$$

$$\left. + \left( (\kappa_2)_{j-k}^{(i)} \hat{B}_k^{(i)} + (\kappa_5)_{j-k}^{(i)} \hat{A}_k^{(i)} + (\kappa_8)_{j-k}^{(i)} \hat{C}_k^{(i)} + (\kappa_{11})_{j-k}^{(i)} \hat{D}_k^{(i)} + (\kappa_{14})_{j-k}^{(i)} \hat{E}_k^{(i)} \right) \right\}, \tag{11b}$$

$$\hat{C}_{j+2}^{(i)} + (\vartheta_3)_0^{(i)} \hat{A}_{j+2}^{(i)} + (\vartheta_6)_0^{(i)} \hat{B}_{j+2}^{(i)} + (\vartheta_9)_0^{(i)} \hat{D}_{j+2}^{(i)} + (\vartheta_{12})_0^{(i)} \hat{E}_{j+2}^{(i)}$$

$$= \frac{-1}{(j+2)(j+1)} \left\{ \sum_{k=0}^{j-1} \left[ (k+2)(k+1) \right. \right.$$

$$\left. \left. \times \left( (\vartheta_3)_{j-k}^{(i)} \hat{A}_{k+2}^{(i)} + (\vartheta_6)_{j-k}^{(i)} \hat{B}_{k+2}^{(i)} + (\vartheta_9)_{j-k}^{(i)} \hat{D}_{k+2}^{(i)} + (\vartheta_{12})_{j-k}^{(i)} \hat{E}_{k+2}^{(i)} \right) \right] \right.$$

$$\left. + \sum_{k=0}^j \left[ (k+1) \left( (\vartheta_1)_{j-k}^{(i)} \hat{C}_{k+1}^{(i)} + (\vartheta_4)_{j-k}^{(i)} \right. \right. \right.$$

$$\left. \left. \times \hat{A}_{k+1}^{(i)} + (\vartheta_7)_{j-k}^{(i)} \hat{B}_{k+1}^{(i)} + (\vartheta_{10})_{j-k}^{(i)} \hat{D}_{k+1}^{(i)} + (\vartheta_{13})_{j-k}^{(i)} \hat{E}_{k+1}^{(i)} \right) \right.$$

$$\left. + \left( (\vartheta_2)_{j-k}^{(i)} \hat{C}_k^{(i)} + (\vartheta_5)_{j-k}^{(i)} \hat{A}_k^{(i)} + (\vartheta_8)_{j-k}^{(i)} \hat{B}_k^{(i)} \right. \right.$$

$$\left. \left. + (\vartheta_{11})_{j-k}^{(i)} \hat{D}_k^{(i)} + (\vartheta_{14})_{j-k}^{(i)} \hat{E}_k^{(i)} \right) \right\}, \tag{11c}$$

$$\hat{D}_{j+2}^{(i)} + (\xi_3)_0^{(i)} \hat{A}_{j+2}^{(i)} + (\xi_6)_0^{(i)} \hat{B}_{j+2}^{(i)} + (\xi_9)_0^{(i)} \hat{C}_{j+2}^{(i)} + (\xi_{12})_0^{(i)} \hat{E}_{j+2}^{(i)}$$

$$= \frac{-1}{(j+2)(j+1)} \left\{ \sum_{k=0}^{j-1} \left[ (k+2)(k+1) \right. \right.$$

$$\left. \left. \times \left( (\xi_3)_{j-k}^{(i)} \hat{A}_{k+2}^{(i)} + (\xi_6)_{j-k}^{(i)} \hat{B}_{k+2}^{(i)} + (\xi_9)_{j-k}^{(i)} \hat{C}_{k+2}^{(i)} + (\xi_{12})_{j-k}^{(i)} \hat{E}_{k+2}^{(i)} \right) \right] \right.$$

$$\left. + \sum_{k=0}^j \left[ (k+1) \left( (\xi_1)_{j-k}^{(i)} \hat{D}_{k+1}^{(i)} + (\xi_4)_{j-k}^{(i)} \right. \right. \right.$$

$$\left. \left. \times \hat{A}_{k+1}^{(i)} + (\xi_7)_{j-k}^{(i)} \hat{B}_{k+1}^{(i)} + (\xi_{10})_{j-k}^{(i)} \hat{C}_{k+1}^{(i)} + (\xi_{13})_{j-k}^{(i)} \hat{E}_{k+1}^{(i)} \right) \right.$$

$$\left. + \left( (\xi_2)_{j-k}^{(i)} \hat{D}_k^{(i)} + (\xi_5)_{j-k}^{(i)} \hat{A}_k^{(i)} + (\xi_8)_{j-k}^{(i)} \hat{B}_k^{(i)} \right. \right.$$

$$\left. \left. + (\xi_{11})_{j-k}^{(i)} \hat{C}_k^{(i)} + (\xi_{14})_{j-k}^{(i)} \hat{E}_k^{(i)} \right) \right\}, \tag{11d}$$

$$\hat{E}_{j+2}^{(i)} + (\xi_3)_0^{(i)} \hat{A}_{j+2}^{(i)} + (\xi_6)_0^{(i)} \hat{B}_{j+2}^{(i)} + (\xi_9)_0^{(i)} \hat{C}_{j+2}^{(i)} + (\xi_{12})_0^{(i)} \hat{D}_{j+2}^{(i)}$$

$$= \frac{-1}{(j+2)(j+1)} \left\{ \sum_{k=0}^{j-1} \left[ (k+2)(k+1) \right. \right.$$

$$\left. \left. \times \left( (\xi_3)_{j-k}^{(i)} \hat{A}_{k+2}^{(i)} + (\xi_6)_{j-k}^{(i)} \hat{B}_{k+2}^{(i)} + (\xi_9)_{j-k}^{(i)} \hat{C}_{k+2}^{(i)} + (\xi_{12})_{j-k}^{(i)} \hat{D}_{k+2}^{(i)} \right) \right] \right.$$

$$\left. + \sum_{k=0}^j \left[ (k+1) \left( (\xi_1)_{j-k}^{(i)} \hat{E}_{k+1}^{(i)} + (\xi_4)_{j-k}^{(i)} \right. \right. \right.$$

$$\left. \left. \times \hat{A}_{k+1}^{(i)} + (\xi_7)_{j-k}^{(i)} \hat{B}_{k+1}^{(i)} + (\xi_{10})_{j-k}^{(i)} \hat{C}_{k+1}^{(i)} + (\xi_{13})_{j-k}^{(i)} \hat{D}_{k+1}^{(i)} \right) \right.$$

$$\left. + \left( (\xi_2)_{j-k}^{(i)} \hat{E}_k^{(i)} + (\xi_5)_{j-k}^{(i)} \hat{A}_k^{(i)} + (\xi_8)_{j-k}^{(i)} \hat{B}_k^{(i)} \right. \right.$$

$$\left. \left. + (\xi_{11})_{j-k}^{(i)} \hat{C}_k^{(i)} + (\xi_{14})_{j-k}^{(i)} \hat{D}_k^{(i)} \right) \right\}, \tag{11e}$$

Careful examination of Eqs. (11a)–(11e) reveals that the coefficients  $\hat{A}_j^{(i)}$ ,  $\hat{B}_j^{(i)}$ ,  $\hat{C}_j^{(i)}$ ,  $\hat{D}_j^{(i)}$  and  $\hat{E}_j^{(i)}$  with  $j \geq 2$  are determined from Eqs. (11a)–(11e) if  $\hat{A}_0^{(i)}$ ,  $\hat{A}_1^{(i)}$ ,  $\hat{B}_0^{(i)}$ ,  $\hat{B}_1^{(i)}$ ,  $\hat{C}_0^{(i)}$ ,  $\hat{C}_1^{(i)}$ ,  $\hat{D}_0^{(i)}$ ,  $\hat{D}_1^{(i)}$ ,  $\hat{E}_0^{(i)}$  and  $\hat{E}_1^{(i)}$  are known. As a result, the solutions of Eqs. (8a)–(8e) in sub-domain  $i$  can be expressed as

$$\hat{U}_{0i}^{(m)}(\theta, z) = \hat{A}_0^{(i)} \hat{U}_{0i0}^{(m)}(\theta, z) + \hat{A}_1^{(i)} \hat{U}_{0i1}^{(m)}(\theta, z) + \hat{B}_0^{(i)} \hat{U}_{0i2}^{(m)}(\theta, z)$$

$$+ \hat{B}_1^{(i)} \hat{U}_{0i3}^{(m)}(\theta, z) + \hat{C}_0^{(i)} \hat{U}_{0i4}^{(m)}(\theta, z)$$

$$+ \hat{C}_1^{(i)} \hat{U}_{0i5}^{(m)}(\theta, z) + \hat{D}_0^{(i)} \hat{U}_{0i6}^{(m)}(\theta, z) + \hat{D}_1^{(i)} \hat{U}_{0i7}^{(m)}(\theta, z)$$

$$+ \hat{E}_0^{(i)} \hat{U}_{0i8}^{(m)}(\theta, z) + \hat{E}_1^{(i)} \hat{U}_{0i9}^{(m)}(\theta, z), \tag{12a}$$

$$\hat{V}_{0i}^{(m)}(\theta, z) = \hat{A}_0^{(i)} \hat{V}_{0i0}^{(m)}(\theta, z) + \hat{A}_1^{(i)} \hat{V}_{0i1}^{(m)}(\theta, z) + \hat{B}_0^{(i)} \hat{V}_{0i2}^{(m)}(\theta, z)$$

$$+ \hat{B}_1^{(i)} \hat{V}_{0i3}^{(m)}(\theta, z) + \hat{C}_0^{(i)} \hat{V}_{0i4}^{(m)}(\theta, z)$$

$$+ \hat{C}_1^{(i)} \hat{V}_{0i5}^{(m)}(\theta, z) + \hat{D}_0^{(i)} \hat{V}_{0i6}^{(m)}(\theta, z) + \hat{D}_1^{(i)} \hat{V}_{0i7}^{(m)}(\theta, z)$$

$$+ \hat{E}_0^{(i)} \hat{V}_{0i8}^{(m)}(\theta, z) + \hat{E}_1^{(i)} \hat{V}_{0i9}^{(m)}(\theta, z), \tag{12b}$$

$$\hat{W}_{0i}^{(m)}(\theta, z) = \hat{A}_0^{(i)} \hat{W}_{0i0}^{(m)}(\theta, z) + \hat{A}_1^{(i)} \hat{W}_{0i1}^{(m)}(\theta, z) + \hat{B}_0^{(i)} \hat{W}_{0i2}^{(m)}(\theta, z)$$

$$+ \hat{B}_1^{(i)} \hat{W}_{0i3}^{(m)}(\theta, z) + \hat{C}_0^{(i)} \hat{W}_{0i4}^{(m)}(\theta, z) + \hat{C}_1^{(i)} \hat{W}_{0i5}^{(m)}(\theta, z)$$

$$+ \hat{D}_0^{(i)} \hat{W}_{0i6}^{(m)}(\theta, z) + \hat{D}_1^{(i)} \hat{W}_{0i7}^{(m)}(\theta, z) + \hat{E}_0^{(i)} \hat{W}_{0i8}^{(m)}(\theta, z)$$

$$+ \hat{E}_1^{(i)} \hat{W}_{0i9}^{(m)}(\theta, z), \tag{12c}$$

$$\hat{\Phi}_{0i}^{(m)}(\theta, z) = \hat{A}_0^{(i)} \hat{\Phi}_{0i0}^{(m)}(\theta, z) + \hat{A}_1^{(i)} \hat{\Phi}_{0i1}^{(m)}(\theta, z) + \hat{B}_0^{(i)} \hat{\Phi}_{0i2}^{(m)}(\theta, z)$$

$$+ \hat{B}_1^{(i)} \hat{\Phi}_{0i3}^{(m)}(\theta, z) + \hat{C}_0^{(i)} \hat{\Phi}_{0i4}^{(m)}(\theta, z)$$

$$+ \hat{C}_1^{(i)} \hat{\Phi}_{0i5}^{(m)}(\theta, z) + \hat{D}_0^{(i)} \hat{\Phi}_{0i6}^{(m)}(\theta, z) + \hat{D}_1^{(i)} \hat{\Phi}_{0i7}^{(m)}(\theta, z)$$

$$+ \hat{E}_0^{(i)} \hat{\Phi}_{0i8}^{(m)}(\theta, z) + \hat{E}_1^{(i)} \hat{\Phi}_{0i9}^{(m)}(\theta, z), \tag{12d}$$

$$\begin{aligned} \hat{\Psi}_{0i}^{(m)}(\theta, z) = & \hat{A}_0^{(i)} \hat{\Psi}_{0i0}^{(m)}(\theta, z) + \hat{A}_1^{(i)} \hat{\Psi}_{0i1}^{(m)}(\theta, z) + \hat{B}_0^{(i)} \hat{\Psi}_{0i2}^{(m)}(\theta, z) \\ & + \hat{B}_1^{(i)} \hat{\Psi}_{0i3}^{(m)}(\theta, z) + \hat{C}_0^{(i)} \hat{\Psi}_{0i4}^{(m)}(\theta, z) \\ & + \hat{C}_1^{(i)} \hat{\Psi}_{0i5}^{(m)}(\theta, z) + \hat{D}_0^{(i)} \hat{\Psi}_{0i6}^{(m)}(\theta, z) + \hat{D}_1^{(i)} \hat{\Psi}_{0i7}^{(m)}(\theta, z) \\ & + \hat{E}_0^{(i)} \hat{\Psi}_{0i8}^{(m)}(\theta, z) + \hat{E}_1^{(i)} \hat{\Psi}_{0i9}^{(m)}(\theta, z), \end{aligned} \quad (12e)$$

Dividing the overall domain of  $\theta$  into  $n$  sub-domains yields  $10n$  coefficients  $\hat{A}_0^{(i)}, \hat{A}_1^{(i)}, \hat{B}_0^{(i)}, \hat{B}_1^{(i)}, \hat{C}_0^{(i)}, \hat{C}_1^{(i)}, \hat{D}_0^{(i)}, \hat{D}_1^{(i)}, \hat{E}_0^{(i)}$  and  $\hat{E}_1^{(i)}$  for  $i=1, 2, \dots, n$ , which are to be determined. The continuity conditions between pairs of adjacent sub-domains provide  $10(n-1)$  equations, which are, at  $\theta = \theta_i$  ( $i=1, 2, \dots, n-1$ )

$$u_{r(i)}^* = u_{r(i+1)}^*, \quad u_{\theta(i)}^* = u_{\theta(i+1)}^*, \quad u_{z(i)}^* = u_{z(i+1)}^*, \quad (13a)$$

$$\sigma_{r\theta(i)}^* = \sigma_{r\theta(i+1)}^*, \quad \sigma_{\theta\theta(i)}^* = \sigma_{\theta\theta(i+1)}^*, \quad \sigma_{z\theta(i)}^* = \sigma_{z\theta(i+1)}^*, \quad (13b)$$

$$D_{\theta(i)}^* = D_{\theta(i+1)}^*, \quad \phi_{\theta(i)}^* = \phi_{\theta(i+1)}^*, \quad B_{\theta(i)}^* = B_{\theta(i+1)}^*, \quad \psi_{\theta(i)}^* = \psi_{\theta(i+1)}^*. \quad (13c)$$

The homogenous boundary conditions at  $\theta = 0$  and  $\theta = \beta$  give another 10 equations. The homogeneous boundary conditions can be specified as follows:

$$\sigma_{r\theta}^* = \sigma_{\theta\theta}^* = \sigma_{z\theta}^* = 0 \text{ (tractionfree) or } u_r^* = u_{\theta}^* = u_z^* = 0 \text{ (clamped)}, \quad (14a)$$

$$\begin{aligned} D_{\theta}^* = B_{\theta}^* = 0 \text{ (magneto – electrically open) or} \\ \phi^* = \psi^* = 0 \text{ (magneto – electrically closed)}, \end{aligned} \quad (14b)$$

**Table 1**  
Material properties.

Parameters	BaTiO <sub>3</sub> [37]	CoFe <sub>2</sub> O <sub>4</sub> [37]
$\bar{c}_{11}$ (GPa)	166	286.0
$\bar{c}_{12}$ (GPa)	77	173.0
$\bar{c}_{13}$ (GPa)	78	170.5
$\bar{c}_{33}$ (GPa)	162	269.5
$\bar{c}_{44}$ (GPa)	43	45.3
$\bar{e}_{15}$ (C/m <sup>2</sup> )	11.6	0
$\bar{e}_{31}$ (C/m <sup>2</sup> )	-4.4	0
$\bar{e}_{33}$ (C/m <sup>2</sup> )	18.6	0
$\bar{d}_{15}$ (N/Am)	0	550.0
$\bar{d}_{31}$ (N/Am)	0	580.3
$\bar{d}_{33}$ (N/Am)	0	699.7
$\bar{\eta}_{11}$ (C <sup>2</sup> /Nm <sup>2</sup> )	$112.0 \times 10^{-10}$	$0.8 \times 10^{-10}$
$\bar{\eta}_{33}$ (C <sup>2</sup> /Nm <sup>2</sup> )	$126.0 \times 10^{-10}$	$0.93 \times 10^{-10}$
$\bar{\mu}_{11}$ (Ns <sup>2</sup> /C <sup>2</sup> )	$5.0 \times 10^{-6}$	$590.0 \times 10^{-6}$
$\bar{\mu}_{33}$ (Ns <sup>2</sup> /C <sup>2</sup> )	$10.0 \times 10^{-6}$	$157.0 \times 10^{-6}$
$\bar{g}_{11}$ (Ns/VC)	0	0
$\bar{g}_{33}$ (Ns/VC)	0	0

**Table 2**  
Convergence of  $\text{Re}[\lambda_1]$  for MEE wedges.

Vertex angle	Material	Boundary conditions	Number of sub-domains	Terms								Published results			
				6	7	8	9	10	12	14	15				
$\beta = 360^\circ$	BaTiO <sub>3</sub> -CoFe <sub>2</sub> O <sub>4</sub> $V_1=50\%$	FOCO	3	0.2482	0.2492	0.2462	0.2489	0.2492	0.2495	0.2499	0.2499	0.2500 [32]			
			4	0.2504	0.2501	0.2500	0.2498	0.2495	0.2500	0.2500	0.2500				
			6	0.2500	0.2499	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500				
			8	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500	0.2500				
			BaTiO <sub>3</sub> -CoFe <sub>2</sub> O <sub>4</sub> $V_1^{(1)}/V_1^{(2)}=50\%/20\%$	FOFO	3	0.4978	0.4916	0.4417	0.4980	0.4998	0.4750		0.5000	0.4999	0.5000 [32]
					4	0.4963	0.4993	0.4999	0.4999	0.4984	0.4999		0.4999	0.4999	
					6	0.4993	0.4999	0.4999	0.5000	0.5000	0.4999		0.5000	0.5000	
					8	0.4999	0.4999	0.4999	0.4999	0.5000	0.5000		0.4999	0.5000	
BaTiO <sub>3</sub> -CoFe <sub>2</sub> O <sub>4</sub> $V_1^{(1)}/V_1^{(2)}=90\%/10\%$		3	0.4962	0.4933	0.4823	0.4887	0.4978	0.4983	0.4999	0.4999	0.5000 [32]				
		4	0.4977	0.4972	0.4986	0.4998	0.4989	0.4998	0.4999	0.4999					
		6	0.4993	0.4996	0.4999	0.5000	0.5000	0.4999	0.5000	0.5000					
		8	0.4999	0.5000	0.4998	0.5000	0.5000	0.5000	0.5000	0.5000					

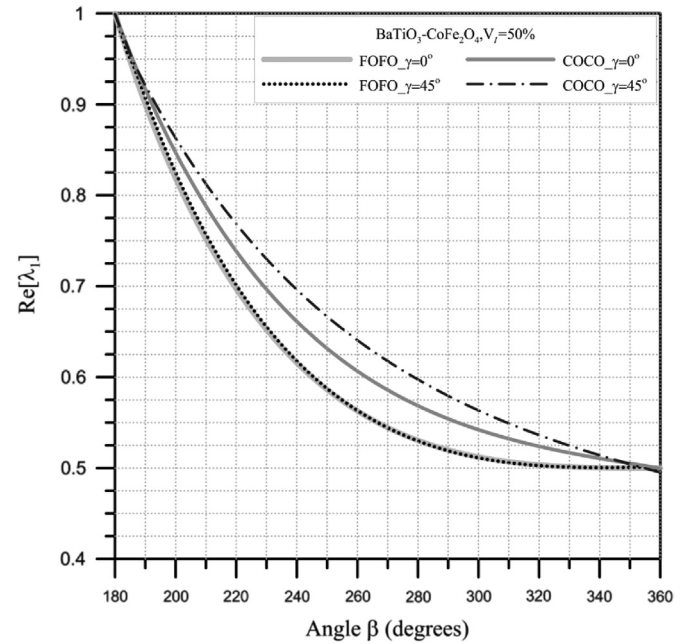
Consequently,  $10n$  homogeneous algebraic equations are established for the  $10n$  coefficients to be determined. To have nontrivial solutions for the coefficients requires zero determinant of the  $10n \times 10n$  matrix that is formed from the coefficients in the established  $10n$  homogeneous algebraic equations. The values of  $\lambda_m$  are the roots of the zero determinant and are determined by the numerical approach of Müller [35]; they are ordered as  $\text{Re}[\lambda_i] \leq \text{Re}[\lambda_{i+1}]$  ( $i=1, 2, 3, \dots$ ).

**4. Verification and comparison**

The BaTiO<sub>3</sub>-CoFe<sub>2</sub>O<sub>4</sub> particulate composite is a typical MEE material and is considered herein. According to the macroscopic mixture rule, the composite material properties of this MEE material are related to the material properties of BaTiO<sub>3</sub> and CoFe<sub>2</sub>O<sub>4</sub> by [36]

$$\bar{\kappa}_{ij} = \bar{\kappa}_{ij}^B V_I + \bar{\kappa}_{ij}^F (1 - V_I), \quad (15)$$

where  $\bar{\kappa}_{ij}^B$  and  $\bar{\kappa}_{ij}^F$  denote the material properties of BaTiO<sub>3</sub> and CoFe<sub>2</sub>O<sub>4</sub> (Table 1), respectively, and  $V_I$  is the volume fraction of the



**Fig. 3.** Variation of  $\text{Re}[\lambda_1]$  with vertex angle for MEE wedges.

inclusion BaTiO<sub>3</sub>. The material properties in Table 1 were taken from Wang et al. [37].

For simplicity, four letters are utilized to specify the boundary conditions along the two radial side faces of a wedge with vertex angle  $\beta$ . The first and third letters indicate mechanical boundary conditions at  $\theta = 0$  and  $\theta = \beta$ , respectively; C and F specify clamped and traction-free, respectively. Similarly, the second and fourth letters represent the magneto-electric boundary conditions at  $\theta = 0$  and  $\theta = \beta$ , respectively; C and O denote magneto-electrically closed and open boundary conditions, respectively.

Since MEE singularities in an MEE wedge that is subjected to the out-of-plane deformation and in-plane electric and magnetic fields have been studied, wedges with the direction of polarization along the

$z$  axis are analyzed herein to verify the proposed solutions. For such wedges, the out-of-plane deformation and in-plane electric and magnetic fields are independent of in-plane deformation and out-of-plane electric and magnetic fields according to Eqs. (6a)–(6e). Notably, Eqs. (8a)–(8e) are independent of  $z$  for an MEE wedge. Consequently, the results of Liu and Chue [32], who assumed that all physical quantities are independent of  $z$ , are used for comparison.

Table 2 shows values of  $\text{Re}[\lambda_1]$  that were obtained by the present approach and by that of Liu and Chue [32] for three wedges with a vertex angle  $\beta = 360^\circ$ . One wedge is made of BaTiO<sub>3</sub> and CoFe<sub>2</sub>O<sub>4</sub> with  $V_I = 50\%$  under FOFO boundary conditions. The other two are under FOFO boundary conditions and made of BaTiO<sub>3</sub> and CoFe<sub>2</sub>O<sub>4</sub> with  $V_I = 50\%$  and  $90\%$  for  $0^\circ \leq \theta < 180^\circ$  and with  $V_I = 20\%$  and  $10\%$  for

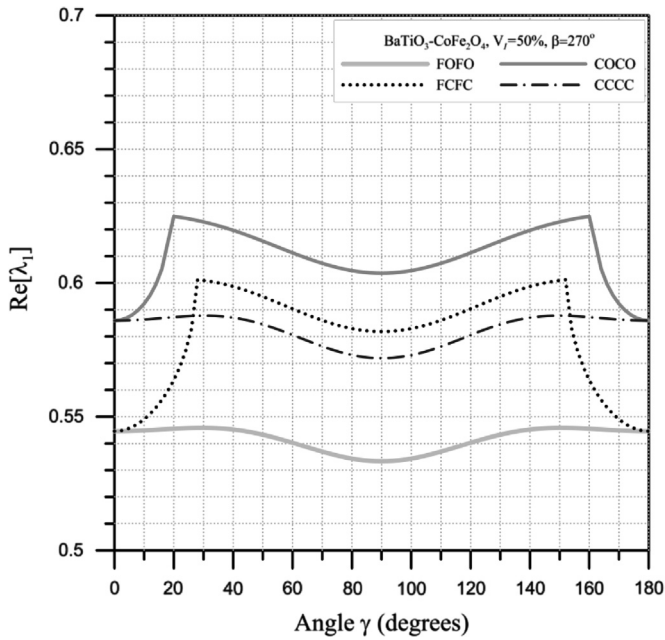


Fig. 4. Variation of  $\text{Re}[\lambda_1]$  with polarization direction for MEE wedges with  $\beta = 270^\circ$ .

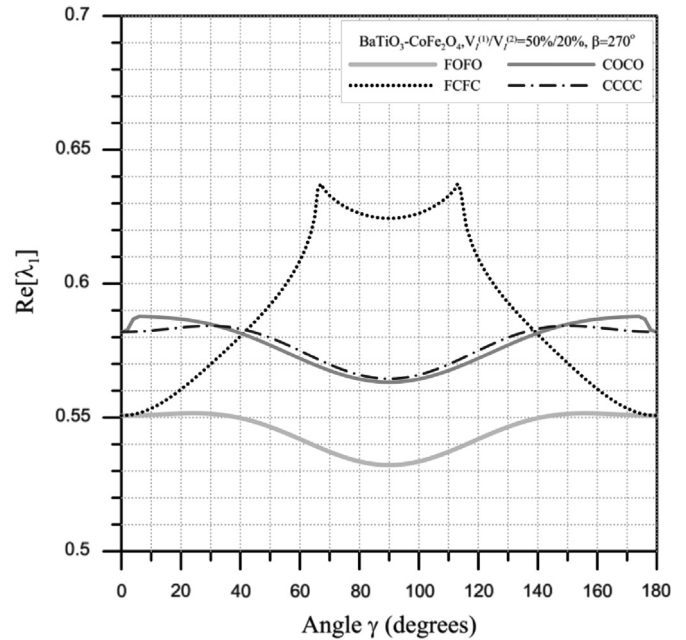


Fig. 6. Variation of  $\text{Re}[\lambda_1]$  with polarization direction for bi-material MEE wedges with  $\beta = 270^\circ$ .

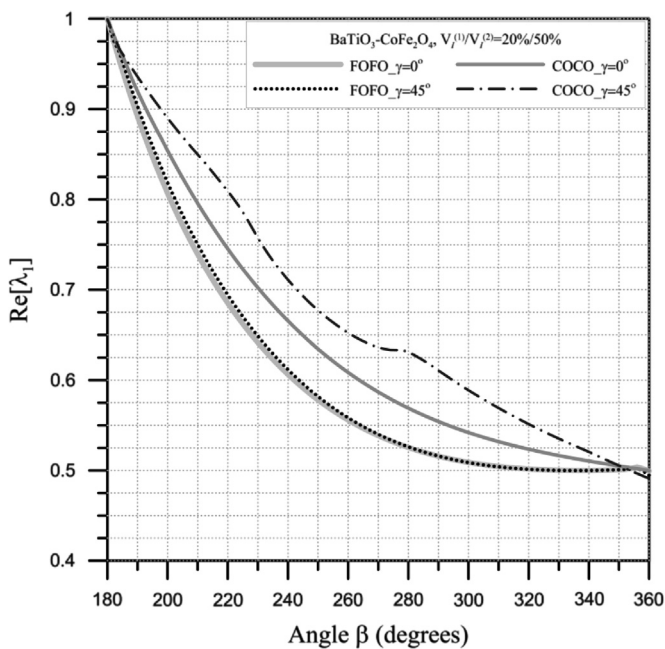


Fig. 5. Variation of  $\text{Re}[\lambda_1]$  with vertex angle for bi-material MEE wedges.

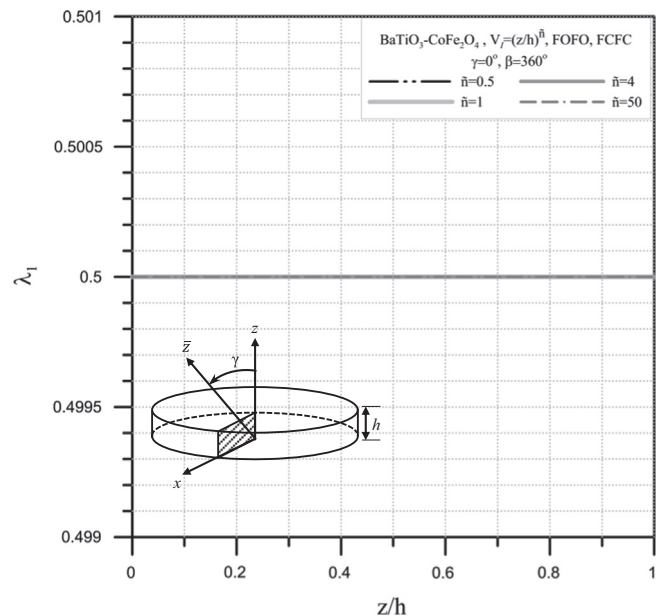


Fig. 7. Distribution of  $\lambda_1$  along the thicknesses of FGME wedges with  $\gamma = 0^\circ$  and  $\beta = 360^\circ$ .



$180^\circ < \theta \leq 360^\circ$ , respectively. Notably, for comparison,  $\bar{\mu}_{11} = 100 \times 10^{-6} \text{Ns}^2/\text{C}^2$  for  $\text{CoFe}_2\text{O}_4$ , as in the work of Liu and Chue [32] was used for the results in Table 2. The present results were obtained using different numbers of sub-domains and polynomial terms for each sub-domain. The convergent results were obtained by increasing the number of sub-domains or the number of polynomial terms for each sub-domain. The convergent results agree excellently with the results of Liu and Chue [32].

### 5. Numerical results and discussion

Following the confirmation of the correctness of the proposed solution, the asymptotic solution is further employed to

investigate the MEE singularities in the MEE and FGMEW wedges, taking into account the effects of the polarization direction, vertex angle, material-property gradient index and boundary conditions. In the following, only  $\text{Re}[\lambda_1]$  is shown in a graphic form because the dominant singularity order at the vertex of a wedge depends on  $\text{Re}[\lambda_1]$ . Notably, the vertical axis of a figure is labeled  $\lambda_1$  when all  $\lambda_1$  are real; otherwise, the vertical axis is labeled  $\text{Re}[\lambda_1]$ . The numerical results were obtained by dividing a wedge into eight sub-domains in  $\theta$  with 10 polynomial terms per sub-domain. The  $\bar{x}-\bar{y}-\bar{z}$  coordinate system is formed by rotating the  $x-y-z$  coordinate system counter-clockwise about the  $y$ -axis through an angle  $\gamma$ , so the angle between the polarization direction of an MEE or FGMEW wedge and its thickness direction is  $\gamma$ .

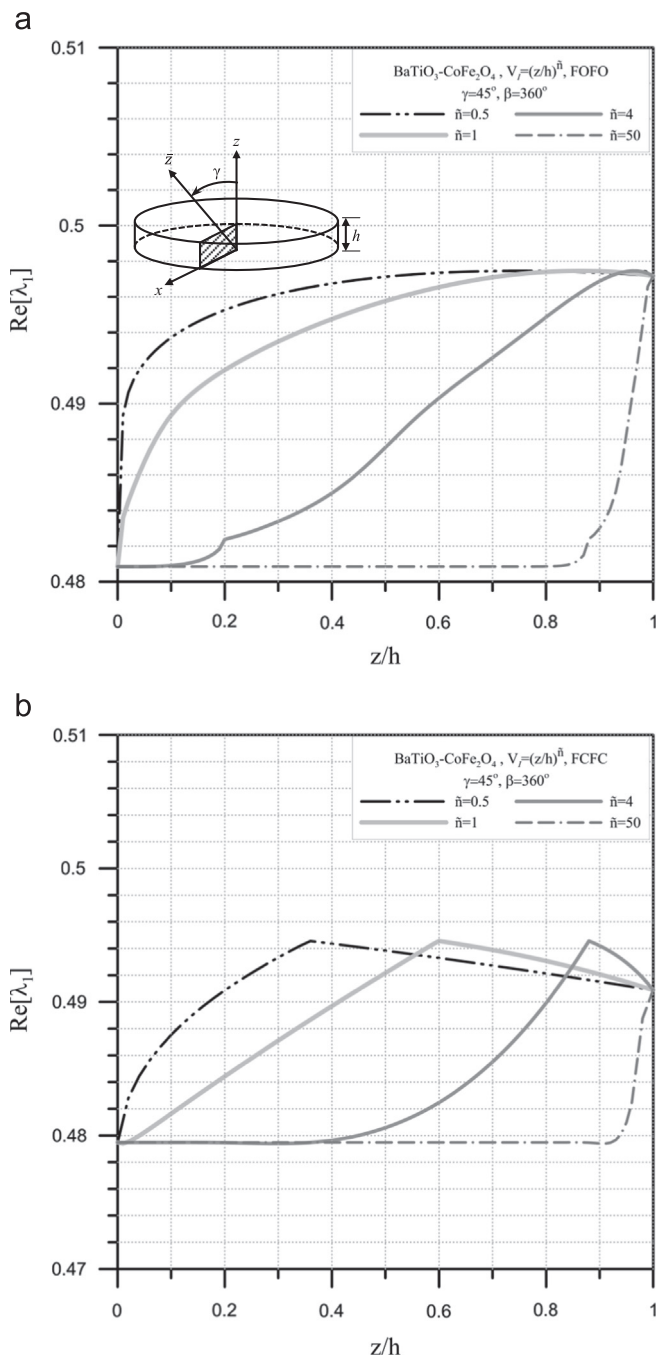


Fig. 8. Distribution of  $\text{Re}[\lambda_1]$  along the thicknesses of FGMEW wedges with  $\gamma = 45^\circ$  and  $\beta = 360^\circ$ : (a) FOFO boundary conditions, and (b) FCFC boundary conditions.

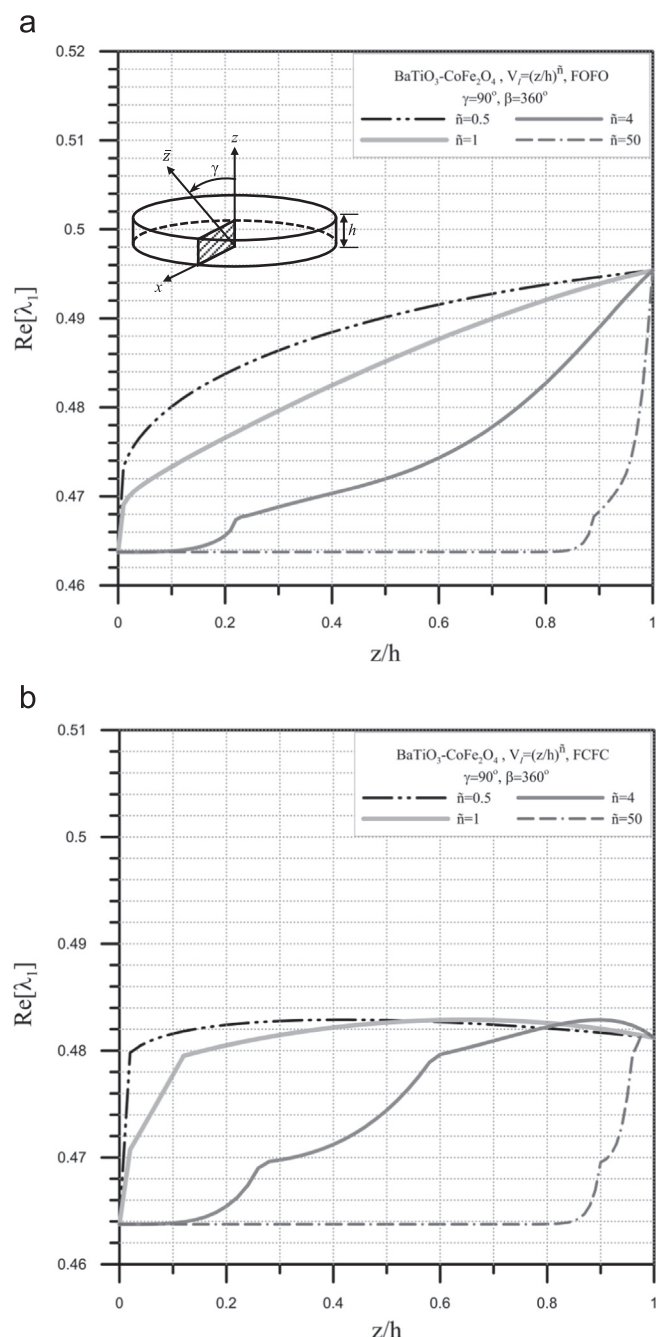


Fig. 9. Distribution of  $\text{Re}[\lambda_1]$  along the thicknesses of FGMEW wedges with  $\gamma = 90^\circ$  and  $\beta = 360^\circ$ : (a) FOFO boundary conditions, and (b) FCFC boundary conditions.

5.1. MEE wedges

Figs. 3 and 4 show the results concerning  $\text{Re}[\lambda_1]$  for  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  wedges with  $V_I = 50\%$  and different polarization directions and boundary conditions. Fig. 3 plots the variation of  $\text{Re}[\lambda_1]$  with the vertex angle  $\beta$ , whereas Fig. 4 depicts the variation of  $\text{Re}[\lambda_1]$  with the polarization direction for wedges with  $\beta = 270^\circ$ . Notably, some values of  $\lambda_1$  in Figs. 3 and 4 are complex. For example, all  $\lambda_1$  values in Fig. 3 for wedges with  $\gamma = 45^\circ$  and COCO boundary conditions are complex, and  $\lambda_1$  values in Fig. 4 for wedges with  $\gamma$  between  $28^\circ$  and  $152^\circ$  under FCFC boundary conditions are complex. These figures demonstrate that the strength of MEE singularities in a wedge generally increases with  $\beta$ , and that free-free mechanical boundary conditions lead to stronger singularities than clamped-clamped boundary conditions. Fig. 4 indicates that changing the direction of polarization can change  $\text{Re}[\lambda_1]$  by up to approximately 10%.

The arrangements considered in Figs. 5 and 6 are the same as those in Figs. 3 and 4, respectively, except that bi-material wedges are considered in Figs. 5 and 6. The bi-material wedges in Fig. 5 are made of  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  with  $V_I = 50\%$  in  $0^\circ \leq \theta < 180^\circ$  and  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  with  $V_I = 20\%$  in  $180^\circ < \theta \leq \beta$ . Fig. 5 also reveals that  $\text{Re}[\lambda_1]$  generally decreases as  $\beta$  increases. Notably, not all values of  $\lambda_1$  are complex for wedges with COCO boundary conditions and  $\gamma = 45^\circ$ , and  $\lambda_1$  is real when  $\beta$  is between  $212^\circ$  and  $336^\circ$ . Fig. 6 considers bi-material wedges with  $\beta = 270^\circ$ , made of  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  with  $V_I = 20\%$  in  $0^\circ \leq \theta < 180^\circ$  and  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  with  $V_I = 50\%$  in  $180^\circ < \theta \leq 270^\circ$ , and indicates that changing the polarization direction can change  $\text{Re}[\lambda_1]$  by up to around 15%.

5.2. FGMEE wedges

As mentioned in Section 1, no investigation of geometrically-induced singularities in an FGMEE wedge has been published. The special feature of the graded spatial compositions of FGMEE materials enables these materials to be used in a very wide range of applications. The distribution of the singularities at the vertex of an FGMEE wedge along its thickness is of particular interest.

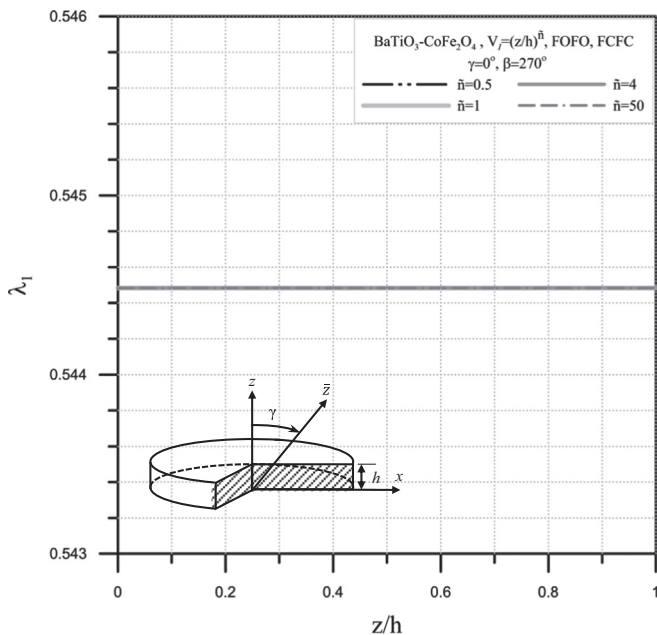


Fig. 10. Distribution of  $\lambda_1$  along the thicknesses of FGMEE wedges with  $\gamma = 0^\circ$  and  $\beta = 270^\circ$ .

FGMEE wedges under consideration herein consist of  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  with  $V_I$  varying along the thickness direction according to a simple power law

$$V_I = \left(\frac{z}{h}\right)^{\tilde{n}}, \tag{16}$$

where  $\tilde{n}$  is the material-property gradient index, which indicates the degree of variation of the material properties along its thickness  $h$ , and  $0 \leq z \leq h$ . The wedges consist of  $\text{CoFe}_2\text{O}_4$  only at their bottom surfaces ( $z=0$ ), and  $\text{BaTiO}_3$  at their top surfaces ( $z=h$ ).

Figs. 7, 8, and 9 display the variations of  $\text{Re}[\lambda_1]$  or  $\lambda_1$  along the thickness of the FGMEE wedges with  $\gamma = 0^\circ, 45^\circ$  and  $90^\circ$ , respectively. The wedges have vertex angle  $\beta = 360^\circ$ , free-free mechanical

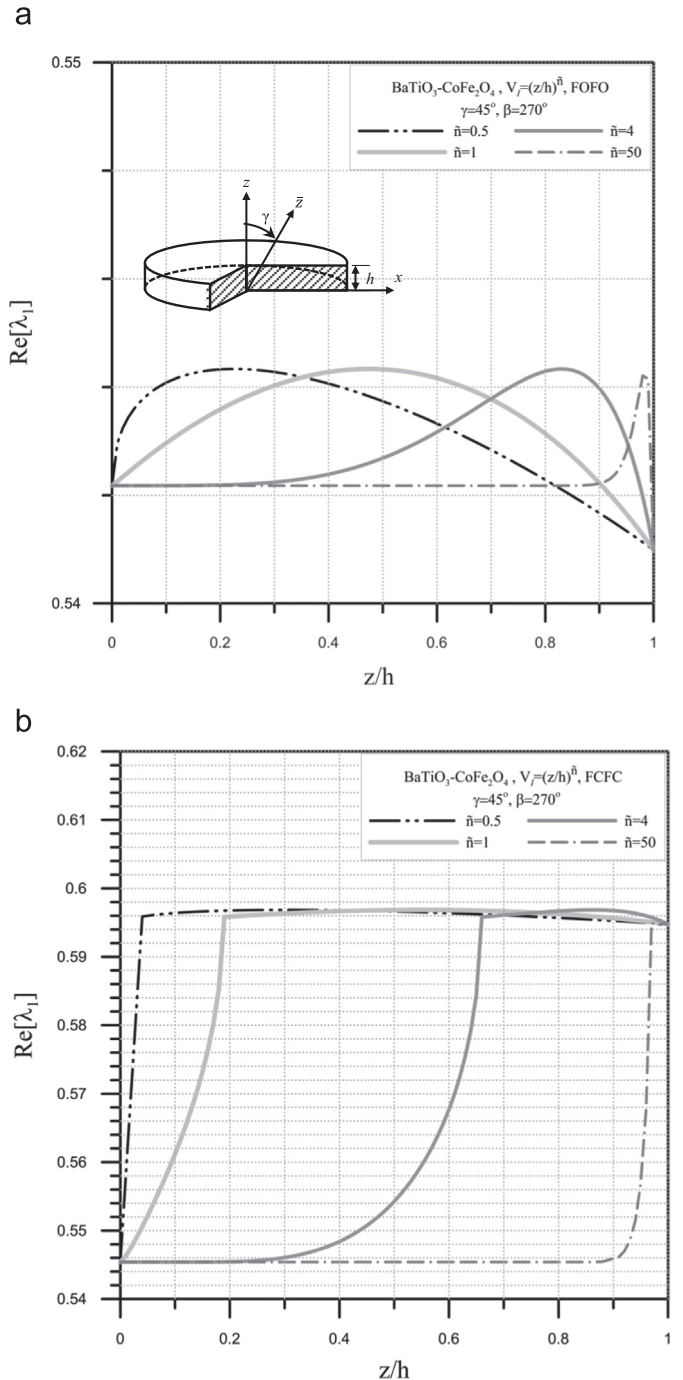


Fig. 11. Distribution of  $\text{Re}[\lambda_1]$  along the thicknesses of FGMEE wedges with  $\gamma = 45^\circ$  and  $\beta = 270^\circ$ : (a) FOFO boundary conditions, and (b) FCFC boundary conditions.

boundary conditions and  $\tilde{n} = 0.5, 1, 4$  and  $50$ . Fig. 7 demonstrates that for wedges with  $\gamma = 0^\circ$  under FOFO and FCFC boundary conditions, the material-property gradient index does not affect the strength of the singularities at the vertex ( $\lambda_1 = 0.5$ ), which remains constant along the thickness direction. Boundary conditions FOFO and FCFC yield identical results. Figs. 8 and 9 reveal that when  $\gamma = 45^\circ$  and  $90^\circ$ , the values of  $\text{Re}[\lambda_1]$  vary with  $z/h$  and  $\tilde{n}$  by less than 7%. The values of  $\text{Re}[\lambda_1]$  for wedges with FOFO boundary conditions generally increase with an increase of  $z/h$  and a decrease in  $\tilde{n}$ , but these trends are not observed under FCFC boundary conditions.

The arrangements considered in Figs. 10, 11 and 12 are the same as those in Figs. 7, 8, and 9, respectively, except that wedges with  $\beta = 270^\circ$  are considered in Figs. 10–12. Fig. 10 reveals that  $\text{Re}[\lambda_1]$  does not depend on  $z/h$  or  $\tilde{n}$  for wedges with  $\gamma = 0^\circ$  under FOFO or FCFC

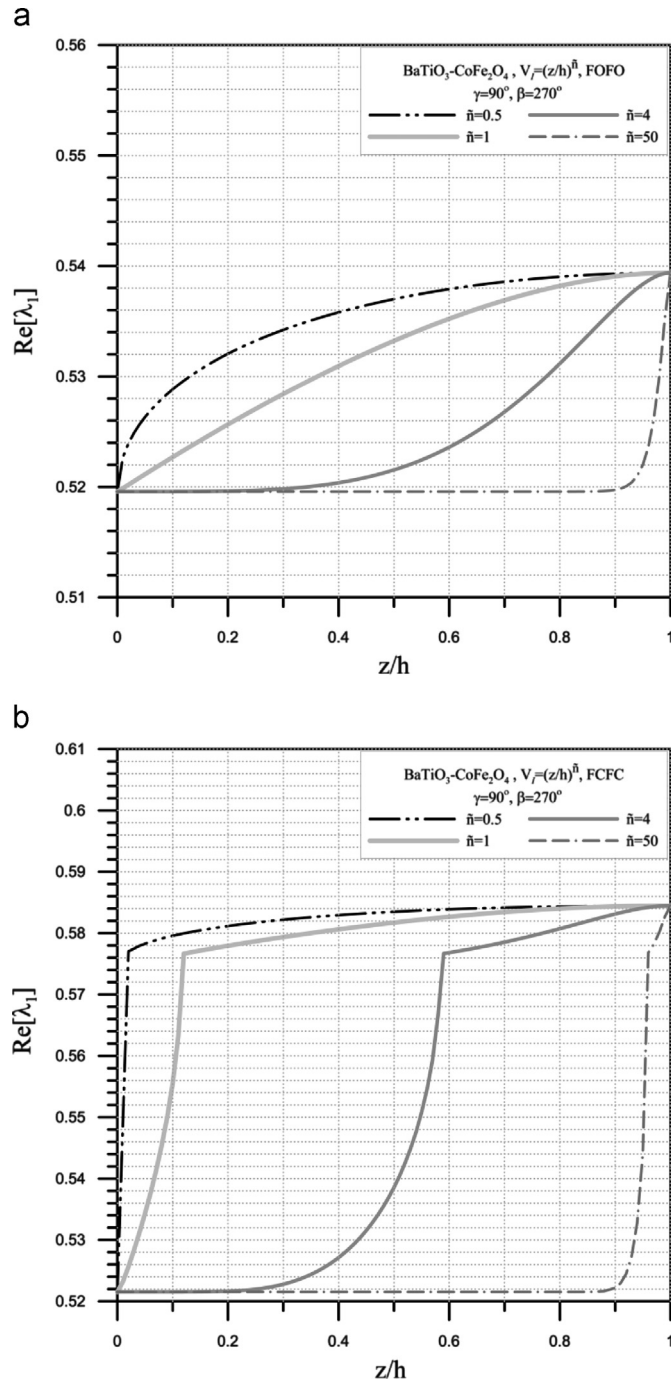


Fig. 12. Distribution of  $\text{Re}[\lambda_1]$  along the thicknesses of FGME wedges with  $\gamma = 90^\circ$  and  $\beta = 270^\circ$ : (a) FOFO boundary conditions, and (b) FCFC boundary conditions.

boundary conditions, and boundary conditions FOFO and FCFC yield identical results. Figs. 11 and 12 discover that  $\text{Re}[\lambda_1]$  may significantly depend on  $z/h$  and  $\tilde{n}$ , and  $\text{Re}[\lambda_1]$  may vary by about 4% and 12% for FOFO and FCFC wedges, respectively. The values of  $\text{Re}[\lambda_1]$  for wedges

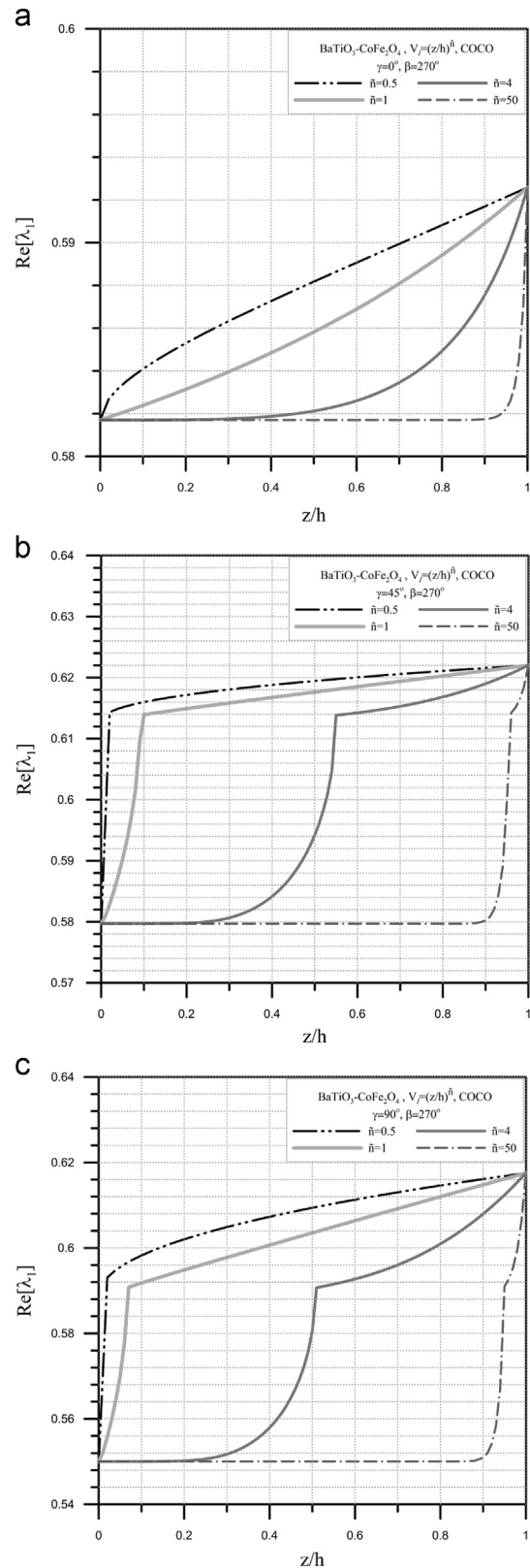


Fig. 13. Distribution of  $\text{Re}[\lambda_1]$  with along the thicknesses of FGME wedges with  $\beta = 270^\circ$  and COCO boundary conditions: (a)  $\gamma = 0^\circ$ , (b)  $\gamma = 45^\circ$ , and (c)  $\gamma = 90^\circ$ .

with  $\gamma = 90^\circ$  generally increase with increasing  $z/h$  and decreasing  $\tilde{n}$ , but wedges with  $\gamma = 45^\circ$  do not exhibit these trends.

To investigate the effects of mechanical boundary conditions on  $\text{Re}[\lambda_1]$ , Fig. 13 depicts the variation of  $\text{Re}[\lambda_1]$  or  $\lambda_1$  along the thickness direction of COCO wedges with  $\beta = 270^\circ$  and various  $\gamma$  ( $\gamma = 0^\circ, 45^\circ$  and  $90^\circ$ ) and  $\tilde{n}$  ( $\tilde{n} = 0.5, 1, 4$  and  $50$ ). The values of  $\text{Re}[\lambda_1]$  generally increase with an increase in  $z/h$  or a decrease in  $\tilde{n}$ . The variations of  $\lambda_1$  with  $z/h$  and  $\tilde{n}$  are less than 2% for wedges with  $\gamma = 0^\circ$ , and  $\text{Re}[\lambda_1]$  may vary by up to 7% and 13% for  $\gamma = 45^\circ$  and  $90^\circ$ , respectively.

### 6. Concluding remarks

Based on three-dimensional magneto-electro-elasticity theory, this study established asymptotic solutions for the geometrically-induced magneto-electro-elastic singularities at the vertex of a rectilinearly polarized wedge that is made of functionally graded magneto-electro-elastic materials. The asymptotic solutions were developed using an eigenfunction expansion approach with the power series solution technique and a domain decomposition technique to solve the three-dimensional equations of motion and Maxwell's equations in terms of mechanical displacement components and electric and magnetic potentials in a cylindrical coordinate system. An arbitrary polarization direction of material yields coupling among in-plane and out-of-plane physical quantities (mechanical displacement, electric and magnetic fields), considerably complicates the asymptotic solutions. The correctness of the solutions was confirmed by performing convergence studies of  $\text{Re}[\lambda_1]$  for  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  wedges with polarization in the thickness direction, and comparing the convergent  $\text{Re}[\lambda_1]$  with the results published for wedges under anti-plane deformation and in-plane electric and magnetic fields.

The proposed solutions were further employed to determine the variations of  $\text{Re}[\lambda_1]$  with the vertex angle ( $\beta$ ) and the position along the thickness ( $z/h$ ) for MEE and FGMEE wedges made of  $\text{BaTiO}_3\text{-CoFe}_2\text{O}_4$  particulate composite under various boundary conditions and with various polarization directions ( $\gamma = 0^\circ, 45^\circ$  and  $90^\circ$ ). For FGMEE wedges, the volume fraction of the inclusion  $\text{BaTiO}_3$  was assumed to vary in the thickness direction in a manner governed by a simple power law with the material-property gradient index, and the effects of the material-property gradient index ( $\tilde{n} = 0.5, 1, 4,$  and  $50$ ) on  $\text{Re}[\lambda_1]$  were examined.

Numerical results reveal that a larger vertex angle yields stronger MEE singularities at the vertex of a wedge, and free-free mechanical boundary conditions lead to stronger singularities than do clamped-clamped boundary conditions. The polarization direction may significantly affect  $\text{Re}[\lambda_1]$ . When FGMEE wedges are polarized along the thickness direction ( $\gamma = 0^\circ$ ),  $\tilde{n}$  and  $z/h$  have no effect on the orders of singularities in the wedges with  $\beta = 270^\circ$  and  $360^\circ$  under FOFO or FCFC boundary conditions. When the thickness direction is not the direction of polarization, the orders of singularities in an FGMEE wedge may depend significantly on  $\tilde{n}$  and  $z/h$ . For example,  $\text{Re}[\lambda_1]$  may vary with  $\tilde{n}$  and  $z/h$  by up to about 12% for a wedge with  $\beta = 270^\circ, \gamma = 90^\circ$  under FCFC boundary conditions. Notably, the variation of orders of singularities with  $z/h$  substantially complicates the determination of stress intensity factors for an FGMEE plate with a V-notch or crack.

### Acknowledgment

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### Appendix A

$$[c] = [\mathbf{T}]_D [\mathbf{K}] [\mathbf{C}] [\mathbf{K}]^T [\mathbf{T}]_E^{-1}, [e] = [\mathbf{T}]_D [\mathbf{L}] [\mathbf{e}] [\mathbf{K}]^T [\mathbf{T}]_E^{-1}, [d] = [\mathbf{T}]_D [\mathbf{L}] [\mathbf{d}] [\mathbf{K}]^T [\mathbf{T}]_E^{-1},$$

$$[\eta] = [\mathbf{T}]_D [\mathbf{L}] [\eta] [\mathbf{L}]^T [\mathbf{T}]_E^{-1}, [\mu] = [\mathbf{T}]_B [\mathbf{L}] [\mu] [\mathbf{L}]^T [\mathbf{T}]_H^{-1}, [g] = [\mathbf{T}]_E [\mathbf{L}] [g] [\mathbf{L}]^T [\mathbf{T}]_B^{-1}$$

where

$$[\mathbf{T}]_D = \begin{bmatrix} \cos^2\theta & \sin^2\theta & 0 & 2\cos\theta\sin\theta & 0 & 0 \\ \sin^2\theta & \cos^2\theta & 0 & -2\cos\theta\sin\theta & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ -\cos\theta\sin\theta & \cos\theta\sin\theta & 0 & \cos^2\theta - \sin^2\theta & 0 & 0 \\ 0 & 0 & 0 & 0 & \cos\theta & \sin\theta \\ 0 & 0 & 0 & 0 & -\sin\theta & \cos\theta \end{bmatrix},$$

$$[\mathbf{T}]_E = \begin{bmatrix} \cos^2\theta & \sin^2\theta & 0 & \cos\theta\sin\theta & 0 & 0 \\ \sin^2\theta & \cos^2\theta & 0 & -\cos\theta\sin\theta & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ -2\cos\theta\sin\theta & 2\cos\theta\sin\theta & 0 & \cos^2\theta - \sin^2\theta & 0 & 0 \\ 0 & 0 & 0 & 0 & \cos\theta & \sin\theta \\ 0 & 0 & 0 & 0 & -\sin\theta & \cos\theta \end{bmatrix},$$

$$[\mathbf{T}]_E = [\mathbf{T}]_D = [\mathbf{T}]_B = [\mathbf{T}]_H = \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

$$[\mathbf{L}] = \begin{bmatrix} \cos(x, \bar{x}) & \cos(x, \bar{y}) & \cos(x, \bar{z}) \\ \cos(y, \bar{x}) & \cos(y, \bar{y}) & \cos(y, \bar{z}) \\ \cos(z, \bar{x}) & \cos(z, \bar{y}) & \cos(z, \bar{z}) \end{bmatrix} = \begin{bmatrix} l_{11} & l_{12} & l_{13} \\ l_{21} & l_{22} & l_{23} \\ l_{31} & l_{32} & l_{33} \end{bmatrix},$$

$$[\mathbf{K}] = \begin{bmatrix} \mathbf{K}_1 & 2\mathbf{K}_2 \\ \mathbf{K}_3 & \mathbf{K}_4 \end{bmatrix}, \quad \mathbf{K}_1 = \begin{bmatrix} l_{11}^2 & l_{12}^2 & l_{13}^2 \\ l_{21}^2 & l_{22}^2 & l_{23}^2 \\ l_{31}^2 & l_{32}^2 & l_{33}^2 \end{bmatrix},$$

$$\mathbf{K}_2 = \begin{bmatrix} l_{12}l_{13} & l_{13}l_{11} & l_{11}l_{12} \\ l_{22}l_{23} & l_{23}l_{21} & l_{21}l_{22} \\ l_{32}l_{33} & l_{33}l_{31} & l_{31}l_{32} \end{bmatrix},$$

$$\mathbf{K}_3 = \begin{bmatrix} l_{21}l_{31} & l_{22}l_{32} & l_{23}l_{33} \\ l_{31}l_{11} & l_{32}l_{12} & l_{33}l_{13} \\ l_{11}l_{21} & l_{12}l_{22} & l_{13}l_{23} \end{bmatrix},$$

$$\mathbf{K}_4 = \begin{bmatrix} l_{22}l_{33} + l_{23}l_{32} & l_{23}l_{31} + l_{21}l_{33} & l_{21}l_{32} + l_{22}l_{31} \\ l_{32}l_{13} + l_{33}l_{12} & l_{33}l_{11} + l_{31}l_{13} & l_{31}l_{12} + l_{32}l_{11} \\ l_{12}l_{23} + l_{13}l_{22} & l_{13}l_{21} + l_{11}l_{23} & l_{11}l_{22} + l_{12}l_{21} \end{bmatrix}.$$

### Appendix B

$$p_1 = \frac{1}{c_{66}} \left( 2\lambda_m c_{16} + \frac{\partial c_{66}}{\partial \theta} \right), \quad p_2 = \frac{1}{c_{66}} \left( \lambda_m^2 c_{11} + \lambda_m \frac{\partial c_{16}}{\partial \theta} - c_{22} + \frac{\partial c_{26}}{\partial \theta} \right),$$

$$p_3 = \frac{c_{26}}{c_{66}}, \quad p_4 = \frac{1}{c_{66}} \left[ (\lambda_m - 1)c_{66} + \lambda_m c_{12} - c_{22} + \frac{\partial c_{26}}{\partial \theta} \right],$$

$$p_5 = \frac{1}{c_{66}} (\lambda_m - 1) \left( \lambda_m c_{16} - c_{26} + \frac{\partial c_{66}}{\partial \theta} \right), \quad p_6 = \frac{c_{46}}{c_{66}},$$

$$p_7 = \frac{1}{c_{66}} \left[ \lambda_m (c_{14} + c_{56}) - c_{24} + \frac{\partial c_{46}}{\partial \theta} \right],$$

$$p_8 = \frac{1}{c_{66}} \lambda_m \left( \lambda_m c_{15} - c_{25} + \frac{\partial c_{56}}{\partial \theta} \right), \quad p_9 = \frac{e_{26}}{c_{66}},$$

$$p_{10} = \frac{1}{c_{66}} \left[ \lambda_m (e_{16} + e_{21}) - e_{22} + \frac{\partial e_{26}}{\partial \theta} \right],$$

$$p_{11} = \frac{1}{c_{66}} \lambda_m \left( \lambda_m e_{11} - e_{12} + \frac{\partial e_{16}}{\partial \theta} \right), \quad p_{12} = \frac{d_{26}}{c_{66}},$$

$$p_{13} = \frac{1}{c_{66}} \left[ \lambda_m (d_{16} + d_{21}) - d_{22} + \frac{\partial d_{26}}{\partial \theta} \right],$$

$$p_{14} = \frac{1}{c_{66}} \lambda_m \left( \lambda_m d_{11} - d_{12} + \frac{\partial d_{16}}{\partial \theta} \right).$$

$$q_1 = \frac{1}{c_{22}} \left( 2\lambda_m c_{26} + \frac{\partial c_{22}}{\partial \theta} \right), \quad q_2 = \frac{1}{c_{22}} (\lambda_m - 1) \left[ (\lambda_m + 1) c_{66} + \frac{\partial c_{26}}{\partial \theta} \right],$$

$$q_3 = \frac{c_{26}}{c_{22}}, \quad q_4 = \frac{1}{c_{22}} \left[ \lambda_m (c_{12} + c_{66}) + c_{66} + c_{22} + \frac{\partial c_{26}}{\partial \theta} \right],$$

$$q_5 = \frac{1}{c_{22}} \left[ (\lambda_m + 1) (\lambda_m c_{16} + c_{26}) + \lambda_m \frac{\partial c_{12}}{\partial \theta} + \frac{\partial c_{22}}{\partial \theta} \right],$$

$$q_6 = \frac{c_{24}}{c_{22}}, \quad q_7 = \frac{1}{c_{22}} \left[ \lambda_m (c_{25} + c_{46}) + c_{46} + \frac{\partial c_{24}}{\partial \theta} \right],$$

$$q_8 = \lambda_m \left[ (\lambda_m + 1) c_{56} + \frac{\partial c_{25}}{\partial \theta} \right],$$

$$q_9 = \frac{e_{22}}{c_{22}}, \quad q_{10} = \frac{1}{c_{22}} \left[ \lambda_m (e_{12} + e_{26}) + e_{26} + \frac{\partial e_{22}}{\partial \theta} \right],$$

$$q_{11} = \frac{1}{c_{22}} \lambda_m \left[ (\lambda_m + 1) e_{16} + \frac{\partial e_{12}}{\partial \theta} \right],$$

$$q_{12} = \frac{d_{22}}{c_{22}}, \quad q_{13} = \frac{1}{c_{22}} \left[ \lambda_m (d_{12} + d_{26}) + d_{26} + \frac{\partial d_{22}}{\partial \theta} \right],$$

$$q_{14} = \frac{1}{c_{22}} \lambda_m \left[ (\lambda_m + 1) d_{16} + \frac{\partial d_{12}}{\partial \theta} \right].$$

$$r_1 = \frac{1}{c_{44}} \left( 2\lambda_m c_{45} + \frac{\partial c_{44}}{\partial \theta} \right), \quad r_2 = \frac{1}{c_{44}} \lambda_m \left( \lambda_m c_{55} + \frac{\partial c_{45}}{\partial \theta} \right), \quad r_3 = \frac{c_{46}}{c_{44}}$$

$$r_4 = \frac{1}{c_{44}} \left[ \lambda_m (c_{14} + c_{56}) + c_{24} + \frac{\partial c_{46}}{\partial \theta} \right],$$

$$r_5 = \frac{1}{c_{44}} \left[ \lambda_m \left( \lambda_m c_{15} + c_{25} + \frac{\partial c_{14}}{\partial \theta} \right) + \frac{\partial c_{24}}{\partial \theta} \right], \quad r_6 = \frac{c_{24}}{c_{44}},$$

$$r_7 = \frac{1}{c_{44}} \left[ \lambda_m (c_{25} + c_{46}) - c_{46} + \frac{\partial c_{24}}{\partial \theta} \right],$$

$$r_8 = \frac{1}{c_{44}} (\lambda_m - 1) \left( \lambda_m c_{56} + \frac{\partial c_{46}}{\partial \theta} \right), \quad r_9 = \frac{e_{24}}{c_{44}},$$

$$r_{10} = \frac{1}{c_{44}} \left[ \lambda_m (e_{14} + e_{25}) + \frac{\partial e_{24}}{\partial \theta} \right], \quad r_{11} = \frac{1}{c_{44}} \lambda_m \left( \lambda_m e_{15} + \frac{\partial e_{14}}{\partial \theta} \right),$$

$$r_{12} = \frac{d_{24}}{c_{44}}, \quad r_{13} = \frac{1}{c_{44}} \left[ \lambda_m (d_{14} + d_{25}) + \frac{\partial d_{24}}{\partial \theta} \right],$$

$$r_{14} = \frac{1}{c_{44}} \lambda_m \left( \lambda_m d_{15} + \frac{\partial d_{14}}{\partial \theta} \right).$$

$$s_1 = \frac{1}{\eta_{22}} \left( 2\lambda_m \eta_{12} + \frac{\partial \eta_{22}}{\partial \theta} \right), \quad s_2 = \frac{1}{\eta_{22}} \lambda_m \left( \lambda_m \eta_{11} + \frac{\partial \eta_{12}}{\partial \theta} \right), \quad s_3 = -\frac{e_{26}}{\eta_{22}},$$

$$s_4 = -\frac{1}{\eta_{22}} \left[ \lambda_m (e_{16} + e_{21}) + e_{22} + \frac{\partial e_{26}}{\partial \theta} \right],$$

$$s_5 = -\frac{1}{\eta_{22}} \left[ \lambda_m \left( \lambda_m e_{11} + e_{12} + \frac{\partial e_{21}}{\partial \theta} \right) + \frac{\partial e_{22}}{\partial \theta} \right]$$

$$s_6 = -\frac{e_{22}}{\eta_{22}}, \quad s_7 = -\frac{1}{\eta_{22}} \left[ \lambda_m (e_{12} + e_{26}) - e_{26} + \frac{\partial e_{22}}{\partial \theta} \right],$$

$$s_8 = -\frac{1}{\eta_{22}} (\lambda_m - 1) \left( \lambda_m e_{16} + \frac{\partial e_{26}}{\partial \theta} \right),$$

$$s_9 = -\frac{e_{24}}{\eta_{22}}, \quad s_{10} = -\frac{1}{\eta_{22}} \left[ \lambda_m (e_{14} + e_{25}) + \frac{\partial e_{24}}{\partial \theta} \right],$$

$$s_{11} = -\frac{1}{\eta_{22}} \lambda_m \left( \lambda_m e_{15} + \frac{\partial e_{25}}{\partial \theta} \right),$$

$$s_{12} = \frac{g_{22}}{\eta_{22}}, \quad s_{13} = \frac{1}{\eta_{22}} \left[ 2\lambda_m g_{12} + \frac{\partial g_{22}}{\partial \theta} \right],$$

$$s_{14} = \frac{1}{\eta_{22}} \lambda_m \left( \lambda_m g_{11} + \frac{\partial g_{12}}{\partial \theta} \right).$$

$$t_1 = \frac{1}{\mu_{22}} \left( 2\lambda_m \mu_{12} + \frac{\partial \mu_{22}}{\partial \theta} \right), \quad t_2 = \frac{1}{\mu_{22}} \lambda_m \left( \lambda_m \mu_{11} + \frac{\partial \mu_{12}}{\partial \theta} \right), \quad t_3 = -\frac{d_{26}}{\mu_{22}},$$

$$t_4 = -\frac{1}{\mu_{22}} \left[ \lambda_m (d_{16} + d_{21}) + d_{22} + \frac{\partial d_{26}}{\partial \theta} \right],$$

$$t_5 = -\frac{1}{\mu_{22}} \left[ \lambda_m \left( \lambda_m d_{11} + d_{12} + \frac{\partial d_{21}}{\partial \theta} \right) + \frac{\partial d_{22}}{\partial \theta} \right],$$

$$t_6 = -\frac{d_{22}}{\mu_{22}}, \quad t_7 = -\frac{1}{\mu_{22}} \left[ \lambda_m (d_{12} + d_{26}) - d_{26} + \frac{\partial d_{22}}{\partial \theta} \right],$$

$$t_8 = -\frac{1}{\mu_{22}} (\lambda_m - 1) \left( \lambda_m d_{16} + \frac{\partial d_{26}}{\partial \theta} \right),$$

$$t_9 = -\frac{d_{24}}{\mu_{22}}, \quad t_{10} = -\frac{1}{\mu_{22}} \left[ \lambda_m (d_{14} + d_{25}) + \frac{\partial d_{24}}{\partial \theta} \right],$$

$$t_{11} = -\frac{1}{\mu_{22}} \lambda_m \left( \lambda_m d_{15} + \frac{\partial d_{25}}{\partial \theta} \right),$$

$$t_{12} = \frac{g_{22}}{\mu_{22}}, \quad t_{13} = \frac{1}{\mu_{22}} \left[ 2\lambda_m g_{12} + \frac{\partial g_{22}}{\partial \theta} \right],$$

$$t_{14} = \frac{1}{\mu_{22}} \lambda_m \left( \lambda_m g_{11} + \frac{\partial g_{12}}{\partial \theta} \right).$$

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