## High Frequency Transistor amplifier Design using In Parameters

by Teh Hua Chang M. S., (張 德 驛) Associate Professor of Chiao-Tung university.

Part 1 Basic Concepts

1 General Analysis:

Analysis of Power Flow

Let 
$$I_1=1+jo$$
 (1) and

$$E_2=a+jb=(L+jM)\frac{-h_{21}}{2h_{22r}}$$

$$E_1 = I_1 h_{11} + E_2 h_{12}$$

(3) 
$$I_2 = I_1 h_{21} + E_2 h_{22}$$

Power out=
$$P_0$$
= $R_e$ ( $-E_2*I_2$ )

$$I_{2} = h_{21}(1+jo) + (L+jM) \frac{-h_{21}}{2h_{22}} h_{22}$$
 (6)

Put Eqs (2) and (6) in Eq. (5)

$$\begin{split} P_{\circ} = & R_{e} \frac{h_{21}^{*} (L - jM)}{2h_{22r}} \left[ h_{21}^{*} + \frac{(L + jM) (-h_{21} h_{22})}{2h_{22r}} \right] \\ = & L \frac{|h_{21}|^{2}}{2h_{22r}} - \frac{(L^{2} + M^{2}) |h_{21}|^{2}}{4h_{22r}} \end{split}$$
(7)

$$L^{2}+M^{2}-2L+\frac{4h_{22r}}{|h_{21}|^{2}}P_{o}=0$$

$$(L-1)^{z}+M^{z}=1-\frac{4h_{zzr}}{|h_{z1}|^{2}}P_{o}$$
 (8)

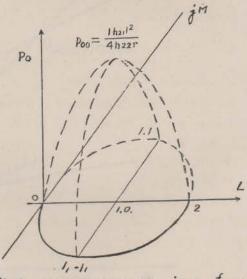
This is an equation of parabo loid with its peak at L=1 M=0 it intersects the LM plane on the unit circle centered at L=1. M=0, The value of Po at L=1, M=0, is

$$P_{00} = -\frac{|h_{31}|^2}{4h_{22r}}$$
 (Fig. 1)

Eq (8) becomes

$$(L-1)^{z}+M^{z}=1-\frac{P_{o}}{P_{oo}}$$
 (9)

This is an equation of concentric Fig.1. Powerout put in a funccircles centered at L=1, M=0, On



(4)

tion of L and M

the LM plane are contours of constant power output. The unit circle is

the locus of zero power output (Fig.2) If the M axis is moved one unit to the right. Eq. (9) becomes

$$L^{12}+M^2=1-\frac{P_0}{P_{00}}$$
 (10) origin at (1.0)

$$P_0 = P_{00} (1 - L^{12} - M^2)$$
 (11) origin at (1.0)

The power input equations are derived as follows

powes input=
$$p_i$$
= $R_e$   $E_1$ \*  $I_1$ = $R_e$   $E_1$ \* (12)  
 $E_1$ = $I_1$   $h_{11}$ + $E_2$   $h_{12}$ = $h_{11}$  (1+jo) + (L+jM)

$$\frac{-h_{21}}{2h_{22r}} h_{12} \quad (13)$$

$$P_1 = h_{11r} + L R_0 - \frac{h_{12}}{2h_{22r}} + M Im \frac{h_{12}}{2h_{22r}} + Im \frac{h_{12}}{2h_{22r}$$

For the origin at L=1, M=0

$$P_{i}=h_{11r}+(L'+1) R_{e}\frac{-h_{12} h_{21}}{2h_{22r}}+M Im \frac{h_{12} h_{21}}{2h_{22r}}$$

$$R_{e}(h_{12} h_{21}) + R_{e}\frac{-h_{12} h_{21}}{2h_{22r}}+M Im \frac{h_{12} h_{21}}{2h_{22r}}$$

$$= h_{11e} - \frac{R_e(h_{12} h_{21})}{2h_{22e}} + L^{\tau} Re \frac{-h_{12} h_{21}}{2h_{22e}} + M Im \frac{h_{12} h_{21}}{2h_{22e}}$$
(15)

$$\mathrm{Let}\ P_{io} {=}\ \frac{2h_{11r}\ h_{22e}}{2h_{22r}} \frac{-R_{e}\ (h_{12}\ h_{21})}{2h_{22r}}\ ,\ A {=} R_{e} \frac{-h_{12}\ h_{21}}{2h_{22r}}\ B {=} \mathrm{Im} \frac{h_{12}\ h_{21}}{2h_{22r}}$$

then 
$$A^2 + B^2 = \frac{|h_{12} h_{21}|^2}{4h_{22r}^2} = |G_2|^2$$
 (16)

$$G_{oo} = \frac{P_{oo}}{P_{io}} = \frac{|h_{21}|^2}{4h_{11r} h_{22r} - 2R_e (h_{12} h_{21})} (17)$$

$$P_i = P_{io} + AL' + BM \quad (18)$$

Eq (18) is the equation of a plane wih 3 intersecting points: him at Pi axis,

$$\frac{2h_{11r}}{R_e} \frac{h_{22r}}{(h_{12} h_{21})}$$
 at L axis, and  $\frac{-2h_{11r}}{Im} \frac{h_{22r}}{(h_{12} h_{21})}$  at M axis.

The input power plane is defines by its gradient and its elevation at L=1 M=0, The elevation at this point is  $P_{io} = \frac{2h_{11r} \ h_{22r} - R_o \ (h_{12} \ h_{21})}{2h_{22r}}$ (19)

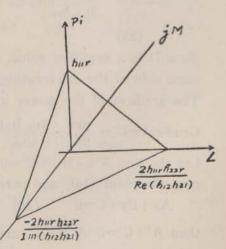


Fig 3. Input Power dia gram

2 The gradient is derived in the following manner The input power plane intercepts the LM plane at a line whose eguation is

$$P_{i}=0=h_{11r}+L R_{e}\frac{-h_{12} h_{21}}{2h_{22r}}+M Im\frac{h_{12} h_{21}}{2h_{22r}}$$
 (20)

Let x=L x=M A= 
$$\frac{R_{\text{e}}(-h_{\text{12}}\ h_{\text{21}})}{2h_{\text{22r}}}$$
 B=Im $\frac{h_{\text{12}}\ h_{\text{21}}}{2h_{\text{22r}}}$  C=h<sub>11r</sub>

Eq (20) becomes Ax+By+c=0

The normal form of this eguotion is

$$x \cos w + y \sin w - p = 0 \tag{22}$$

where 
$$\cos w = \frac{A}{-\sqrt{A^2 + B^2}} \sin w = \frac{B}{-\sqrt{A^2 + B^2}} - p = \frac{C}{-\sqrt{A^2 + B^2}}$$
 (23)

The perpeudicular distance D from a point (x1, y1) to this lins is

$$D=x_{1} \cos w+y_{1} \sin w-p \qquad (24)$$

$$=\cos w-p \text{ at } x_{1}=1, y_{1}=0$$

$$-p=\frac{C}{-1/A^{2}+B^{2}}=\frac{-2h_{11r} h_{22r}}{|h_{12} h_{21}|}$$

$$\cos w=\frac{R_{e}(-h_{12} h_{21})}{-|h_{12} h_{21}|}+\frac{-2h_{11r} h_{22r}}{|h_{12} h_{21}|}$$

$$\therefore D=\frac{-R_{e}(-h_{12} h_{21})}{|h_{12} h_{21}|}+\frac{-2h_{11r} h_{22r}}{|h_{12} h_{21}|}$$

$$=-\frac{2h_{11r} h_{22r}-R_{e}(h_{12} h_{21})}{|h_{12} h_{21}|}=-\frac{1}{C} \text{ Fig. 4 Gradient line Diagram}$$

$$(25)$$

since D is a negative value, the origin and the point (1.0) are at the same side of the intercepting line.

The gradient of the power input plane is defines as

Gradient=
$$G_2 = \frac{\text{pio}}{|D|} = \frac{|h_{12} \ h_{21}|}{2h_{22r}}$$
 (26)

Let the line A'x+B'y+C'=0 (27)

pass the point (1.0) and perpendicular to line

$$Ax + By + C = 0 \tag{21}$$

then A'+C'=0 A'=-C' and m= $-\frac{1}{m'}$ 

m is the slope of line (21). m' is the slope of the line (27)

$$m = \frac{A}{B}$$
  $m' = \frac{A'}{B'}$   $\therefore \frac{A}{B} = -\frac{B'}{A'}$ 

The equation of line (27) which is perpendicular to line (21)

is 
$$A'x+B'y-A'=0$$
  $x+\frac{B'}{A'}y-1=0$ 

or 
$$x - \frac{A}{B}y - 1 = 0$$

∴Bx-Ay-B=0 (28) gradient line with its origin at (0.0) change its origin from (0.0) to (1.0)

$$B(x'+1)-Ay-B=0$$
  $Bx'-Ay=0$  (29) origin at (1.0)

$$Tan\theta = \frac{y}{x'} = \frac{B}{A} = -\frac{Im (-h_{12} h_{21})}{R_{\circ}(-h_{12} h_{21})}$$
(30)

$$\theta = -\text{Ang} (-h_{12} h_{21})$$
 (31)

The Gradient of power input 
$$G_r = \left| \frac{h_{12} h_{21}}{2h_{22r}} \right| e^{j\theta}$$
 (32)

3 The derivation of the stability factor c is as follows The gradient line equation or LM plane with its origin at (0.0) from Eq (28)

$$\operatorname{Im} \frac{(h_{12} \ h_{21})}{2h_{22r}} (L-1) + \operatorname{Re} \frac{(h_{12} \ h_{21})}{2h_{22r}} M = 0$$
 (33)

To find the intercepting points of the unit circle on the LM plane by the gradient line

From Eq (10) with po=0

$$(L-1)^2 + M^2 = 1$$
 (34)

From Eq. (33) and Eq. (34) to solve for M and L

$$M = \pm \frac{Im (h_{12} h_{21})}{|h_{12} h_{21}|} \qquad L = 1 \mp \frac{R_e (h_{12} h_{21})}{|h_{12} h_{21}|}$$
(35)

Take (-) sign (at lower point)

$$M\!=\!-\frac{Im\;(h_{12}\;h_{21})}{|h_{12}\;h_{21}|} \qquad L\!=\!1\!+\!\frac{R_{\text{e}}\;(h_{12}\;h_{21})}{|h_{12}\;h_{21}|}$$

Put into Eq (14)

$$p_{i} = h_{11r} - \frac{R_{e} (h_{12} h_{21})}{2h_{22r}} - \frac{|h_{12} h_{21}|}{2h_{22r}} = p_{1o} - \frac{|h_{12} h_{21}|}{2h_{22r}}$$
(36)

$$C = \frac{p_{1o} - p_{i}}{p_{1o}} = 1 - \frac{p_{i}}{p_{1o}} = \frac{|h_{12} h_{21}|}{2h_{11r} h_{22r} - R_{e} (h_{12} h_{21})} = \frac{2p_{oo}}{p_{1o}} \left| \frac{h_{12}}{h_{21}} \right|$$
(37-a)

Take (+) sign (at upper poivt)

$$L = 1 - \frac{R_{e} \ (h_{12} \ h_{21})}{|h_{12} \ h_{21}|} \qquad M = \frac{Im \ (h_{12} \ h_{21})}{|h_{12} \ h_{21}|}$$

$$p_i = \frac{2h_{11r} \ h_{22r} - R_e \ (h_{12} \ h_{21})}{2h_{22r}} + \frac{|h_{12} \ h_{21}|}{2h_{22r}} = p_{io} + \frac{|h_{12} \ h_{2i}|}{2h_{22r}}$$

$$C = \frac{p_{i} - p_{io}}{p_{io}} = \frac{|h_{12} \ h_{21}|}{2h_{11r} \ h_{22r} - R_{e} \ (h_{12} \ h_{21})}$$
(37-b)
$$G_{oo} = \frac{p_{oo}}{p_{io}} = \frac{C}{2} \left| \frac{h_{21}}{h_{12}} \right|$$
(38)
$$com \ Eq. (18) \ (26) \ and \ (37)$$

From Eq. (18) (26) and (37)  
we get 
$$|G_r| = CP_{io} \text{ or } G_r = CP_{io} e^{j\theta}$$
 (39)

4 The derivation of the maximum gain is as follows

The maximum power output occurs at the apex of the paraboloid. but the maximum gain does not occur at this ponit. since the slope of the input power plane near the ponit (1,0) greater than that of the paraboloid. There must be a point at which the maximum gain will occur.

$$\begin{array}{l} p_o = p_{oo} \ (1 - L'^2 - M^2) \ (11) \\ p_i = AL' + BM + p_{io} \ (18) \end{array} \right\} \ \text{origin at} \ (1.0) \\ G = \frac{p_o}{p_i} = \frac{p_{oo} \ (1 - L'^2 - M^2)}{AL' + BM + p_{io}} \ (40) \\ \frac{\partial G}{\partial L'} = 0 \ \partial L' \ (L'A + BM + p_{io}) + A(1 - L'^2 - M^2) = 0 \ (41) \\ \frac{\partial G}{\partial M} = 0 \ \partial M \ (L'A + BM + p_{io}) + B(1 - L'^2 - M^2) = 0 \ (42) \\ \text{Solve Eq.} (41) \ \text{and Eq.} (42) \ \text{we get} \\ AM = BL' \qquad \frac{B}{A} = \frac{M}{L'} = \tan\theta \ (43) \\ \text{and} \ (A^2 + B^2) L'^2 + 2Ap_{io} \ L' + A^2 = 0 \ (44) \\ L' = \frac{-2Ap_{io} \pm \sqrt{4A^2 \ p_{io}^2 - 4A^2 \ (A^2 + B^2)}}{2(A^2 + B^2)} = A \frac{-p_{io} + \sqrt{p_{io}^2 - (A^2 + B^2)}}{(A^2 + B^2)} \\ = -A \frac{p_{io} - p_{io}\sqrt{1 - c^2}}{(p_{io} \ c)^2} = -A \frac{1 - \sqrt{1 - c^2}}{p_{io} \ c^2} = \frac{-R_e \ (h_{12} \ h_{21})}{|h_{12} \ h_{21}|} \frac{1 - \sqrt{1 - c^2}}{c} \\ = -d \ \cos\theta \ (45) \\ M = -B \frac{1 - \sqrt{1 - c^2}}{p_{io} \ c^2} = \frac{-B}{|G_r|} \frac{1 - \sqrt{1 - c^2}}{c} = \frac{Im \ (h_{12} \ h_{21})}{|h_{12} \ h_{21}|} \frac{1 - \sqrt{1 - c^2}}{c} \\ = -d \ \sin\theta \ (46) \\ \therefore \ (L'^2 + M^2)^{\frac{1}{2}} = -\frac{1 - \sqrt{1 - c^2}}{c} = -d \ (47) \end{array}$$

This point  $(L'=-d\cos\theta, M=-d\sin\theta)$  whose distance from the axis at L=1 M=0, is -d gives the maximum power gain. as shown in Fig. 5 The power output at the point is

$$p_{o} = p_{oo}(1 - L^{12} - M^{2}) = p_{oo} (1 - \frac{(1 - \sqrt{1 - c^{2}})}{c^{2}}) = p_{oo}(1 - d^{2})$$

$$p_{j} = p_{io} + AL' + BM = p_{io} - A^{2} \frac{1 - \sqrt{1 - c^{2}}}{p_{io} c^{2}} - B^{2} \frac{1 - \sqrt{1 - c^{2}}}{p_{io} c^{2}}$$

$$= p_{io}[1 - (1 - \sqrt{1 - c^{2}})] = p_{io}\sqrt{1 - c^{2}}$$

$$(49)$$

pi may be written in the form

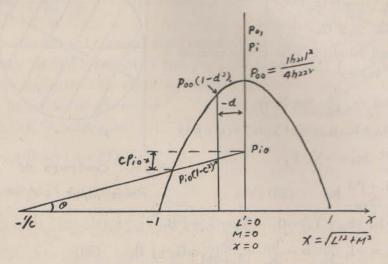


Fig. 5 Power Relation along the gradient line

$$p_{i} = p_{i_{0}} \left(1 + \frac{A}{p_{i_{0}}} L' + \frac{B}{p_{i_{0}}} M\right)$$

$$= p_{i_{0}} \left(1 + \frac{\sqrt{A^{2} + B^{2}}}{p_{i_{0}}} \sqrt{L'^{2} + M^{2}}\right)$$

$$= p_{i_{0}} \left(1 + \frac{|G_{r}|}{p_{i_{0}}} x\right) = p_{i_{0}} (1 + cx) \qquad (50)$$
and  $G_{r} = \left|\frac{h_{12}}{2h_{22r}} h_{21}\right| e^{j\theta} \qquad (32)$ 

From Eqs (32) and Eq (50) for The particular gradient which corresponds to angle  $\theta$ , the contours of constant power input are shown in Fig. 6 The optimum gain is

Gopt = 
$$\frac{p_o}{p_i} = \frac{p_{oo} (1-d^2)}{p_{io} (1-c^2)^{\frac{1}{2}}} = \frac{p_{oo}}{p_{io}} \frac{2}{c^2} (1-\sqrt{1-c^2})$$
  
=  $G_{oo} \frac{2}{c^2} (1-\sqrt{1-c^2})$  (51)

$$K_q = \frac{G_{opt}}{G_{oo}} = \frac{2}{c^2} (1 - \sqrt{1 - c^2}) = \frac{2}{c} d$$
 (52)

$$d = \frac{c}{2} K_0 \qquad (53)$$

when c approaches 1, d approaches

1, 
$$\frac{d}{c} = 1 - \frac{\sqrt{1 - c^2} (1 - \sqrt{1 - c^2})}{c^2} \le 1$$

5 The load admittance is casily related to LM values

$$Y_L$$
 being  $-\frac{I_2}{E_2}$  we have

$$I_2 {=} I_1 \ h_{21} {+} E_2 \ h_{22} {=} (1 {+} jo) h_{21} {+} (L {+} jM)$$

$$\frac{-h_{21}}{2h_{22r}} h_{22} = -Y_L E_2$$
-y L+jM 1

$$=Y_{L}\frac{L+jM}{2h_{22r}} h_{21}$$
 (55)

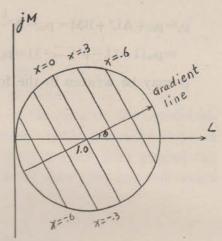


Fig 6. Contours of constant Power input at a angle

$$I_{\scriptscriptstyle 1} \ h_{\scriptscriptstyle 21} {+} E_{\scriptscriptstyle 2} \ (h_{\scriptscriptstyle 22} {+} Y_{\scriptscriptstyle L}) {=} 0 \qquad Y_{\scriptscriptstyle L} {=} G_{\scriptscriptstyle L} {+} j \ B_{\scriptscriptstyle L}$$

$$h_{22} + Y_L = -I_1 \frac{h_{21}}{E_2} = -\frac{h_{21}}{E_2} = \frac{2h_{22r}}{L + jM} = G_2 + j B_2$$
 (56)

$$G_2 + j B_2 = \frac{2h_{22r} L}{L^2 + M^2} - j \frac{2h_{22r} M}{L^2 + M^2}$$
 (57)

$$G_2 = \frac{2h_{22r} L}{L^2 + M^2}$$
 :  $L^2 + M^2 - \frac{2h_{22r}}{G_2} L = 0$ 

$$\therefore (L - \frac{h_{22r}}{G_2})^2 + M^2 = (\frac{h_{22r}}{G_2})^2$$
 (58)

This is an equation of constant G2 circle

$$B_2 = \frac{-2h_{22r} M}{L^2 + M^2}$$
  $L^2 + M^2 + \frac{2h_{22r} M}{B_2} = 0$ 

$$L^{2} + (M + \frac{h_{22r}}{B_{2}})^{2} = (\frac{h_{22r}}{B_{2}})^{2}$$
 (59)

This is an equation of constant B2 circle

$$G_2 = h_{22r} + G_L$$
  $B_2 = h_{22i} + B_L$  (60)

From Eqs (58) and (59) we can draw loci of constant real and imaginary parts of  $G_2+j$   $B_2$  which are mutually orthogonal circles in the LM plane as in smith Chart.

Loci of constant G2 and loci of constant B2 in the LM plane are

shown is the Figure 7
The optimum load admittance is

$$Y_{L} \text{ opt} = -h_{22} - I_{1} \frac{h_{21}}{E_{2}} = -h_{22} + \frac{2h_{22r}}{L + jM}$$

$$= -h_{22} + \frac{2h_{22r}}{(1 - d\cos\theta - j d\sin\theta)} = -h_{22} + \frac{2h_{22r}}{1 - de^{j\theta}}$$

$$= -h_{22} + \frac{2h_{22r}}{1 - \frac{ck_{g}}{2}e^{j\theta}}$$
(61)

6 The relationship between the input impedance of the terminated two port structure and the LM plane is found by the following development

$$E_i = I_i h_{ii} + E_2 h_{i2} = 2_{in}, I_i = 1 + jo (1) and (3)$$

$$2_{in} = (1+jo)h_{11} + (L+jM) \frac{-h_{12} h_{21}}{2h_{22r}}$$
 (61)

$$2_{in} - h_{11} = R_1 + jX_1 = (L + jM) \frac{-h_{12} h_{21}}{2h_{22r}}$$
 (62)

$$\frac{R_1 + jX_1}{\left|\frac{h_{12} \ h_{21}}{2h_{22r}}\right|} = \frac{R_1 + jX_1}{|G_r|} = (L + jM) e^{-j\theta}$$
 (63)

The rectangular grid in shown in Fig. 8

this figure on a transparent overlay

is convenient for reading  $\frac{R_1}{|G_r|} + j \frac{X_1}{|G_r|}$  and  $\frac{X_1}{|G_r|} = \frac{X_1}{|G_r|}$  for any point in the LM plane 1.6 The L axis is put at  $-\theta$  with respect to the  $R_1$  axis

The optimum source impedance is

$$\begin{aligned} &2_{s \text{ opt}} = 2_{in} * = (h_{11} + (L + jM) \frac{-h_{12} h_{21}}{2h_{22r}}) * \\ &= (h_{11} + (1 + L' + jM) \frac{-h_{12} h_{21}}{2h_{22r}}) * \end{aligned}$$

$$= (h_{11} - \frac{h_{12} h_{21}}{2h_{22r}} (1 - d\cos\theta - jd\sin\theta))$$

$$= (h_{11} - \frac{h_{12} \ h_{21}}{2h_{22r}} (1 - de^{\theta \mathbf{j}})) *$$

$$= (h_{11} - \frac{h_{12}}{2h_{22r}} \frac{h_{21}}{1 - \frac{ck_g}{2}} e^{j\theta}))^*$$
 (64)

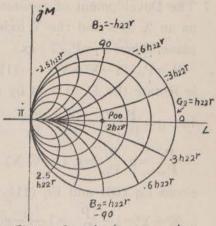


Fig 7. Constant G2 and B2 Contour

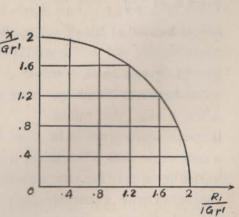


Fig 8 Input Impedance overlay

7 The Development of constant gain circles If we use the gradient line as an X axis and the Y axis perpendicular to it at L=1 M=0 on L M plane, Then  $P_1=P_{10}(1+cx)$  (50)

$$P_0 = P_{00} (1 - X^2 - Y^2)$$
 (11)

ie Rotate the L' M axis by an angle  $\theta$  to get X Y axis

Let 
$$g = \frac{P_o/P_i}{P_{oo}/P_{io}} = \frac{P_o}{P_{oo}} = \frac{P_{io}}{P_i}$$
 (65)

$$\frac{P_o}{P_{00}} = g \frac{P_1}{P_{10}} = g (1+C X)$$
 (66)

From Eq (66) and Eq (11) we get

$$X^{2}+Y^{2}=1-\frac{P_{o}}{P_{oo}}=1-g-gcx$$

$$1-g=X^2+gcx+Y^2$$
  $1-g+\left(\frac{gc}{2}\right)^2=X^2+gcx+\left(\frac{gc}{2}\right)^2+Y^2$ 

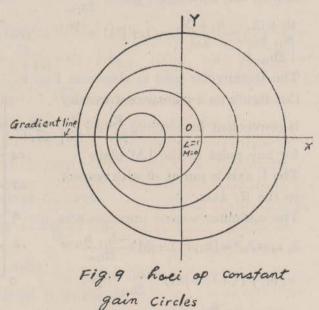
$$\therefore \left( \times + \frac{gc}{2} \right)^2 + Y^2 = 1 - g + \frac{gc}{2} = (Radius)^2$$
 (67)

This is the equation for constant gain circle with its radius equal to

$$\sqrt{1-g+\left(\frac{gc}{2}\right)^2}$$
 and its

center located at  $X = -\frac{gc}{2}$ , Y = 0,

If c<1, g can have any value between 0 and kg, when g=kg, the radius is zero, when g=0 it is a unit circle thus when g varies from 0 to kg, the center of the constant gain circle moves away



along the x axis from the center of the unit circle to  $-\frac{gc}{2}$  at which point its radius is reduced to zero and The sensitivty curves can be constructed on the L M plane, sensitivity is definied as the ratio of the percentage change in input immittance to the percentage change in

load immittance

$$\delta = \frac{\frac{dY_{in}}{Y_{in}}}{\frac{dY_{L}}{Y_{L}}} = \begin{vmatrix} Y_{L} \\ y_{22} + Y_{L} \end{vmatrix} \begin{vmatrix} y_{11r} \\ y_{11} \end{vmatrix} \begin{vmatrix} y_{12} & y_{21} \\ y_{22} + Y_{L} & y_{11r} & y_{22r} \\ y_{22r} + y_{11} & y_{11r} & y_{22r} & y_{11r} & y_{22r} \\ y_{22r} + y_{11} & y_{11r} & y_{22r} & y_{21} \\ y_{22r} + y_{11} & y_{11r} & y_{22r} & y_{21} \end{vmatrix} = \frac{|h_{11r}|}{|h_{11}|} \begin{vmatrix} h_{11r} & h_{12} & h_{21r} \\ h_{22r} + Y_{L} & h_{11r} & h_{12} & h_{21} \\ h_{22r} + Y_{L} & h_{11r} & h_{12} & h_{21} \\ h_{11r} & h_{12r} & h_{22r} & y_{21} \end{vmatrix} = \frac{|h_{12} & h_{21}|}{|h_{11}|} \begin{vmatrix} (69) & \text{when } Y_{L} \rangle h_{22} & (\text{or } y_{22}) \end{vmatrix}$$

$$\frac{|y_{12} & y_{21}|}{|y_{11}|} = \frac{|h_{12} & h_{21}|}{|h_{11}|} \begin{vmatrix} h_{11r} & h_{12} & h_{21} \\ h_{11r} & h_{22r} \end{vmatrix} + h_{22} = \frac{2h_{22r}}{L + jM} \qquad (56)$$

$$Y_{L} = \frac{|h_{12} & h_{21}|}{|h_{11}|} & Y_{L} + h_{22} = \frac{|h_{12} & h_{21}|}{|h_{11}|} + h_{22} = \frac{2h_{22r} & L}{L^{2} + M^{2}} \qquad (56)$$

$$Let G\delta + jB\delta = |Y_{L}| + h_{22} = \frac{|h_{12} & h_{21}|}{|h_{11}|} + h_{22} = \frac{2h_{22r} & L}{L^{2} + M^{2}} - j \frac{2h_{22r} & M}{L^{2} + M^{2}} \qquad (69)$$

$$\therefore G\delta = \frac{2h_{22} & L}{L^{2} + M^{2}} \qquad L^{2} + M^{2} - \frac{2h_{22} & L}{G\delta} = 0$$

$$\left(L - \frac{h_{22r}}{G\delta}\right)^{2} + M^{2} = \left(\frac{h_{22r}}{G\delta}\right)^{2} \qquad (70)$$

$$G\delta = \frac{|h_{12} & h_{21}|}{|h_{11}|} \frac{h_{21}}{\delta} + h_{22r} \qquad B\delta = h_{221} \qquad (71)$$

Eq (70) is an equation of constant  $G\delta$  circle similar to Eq (58) the loci of constant Gδ in the L M plane is the sauce as the G2 circles in Fig. 7 sensitivity is a measure of non unilateralness" it has significance in multistage IF strip design. Sensitivity contourt define the area in which a given loade can be placed to satisfy gain and sensitivity requirments,  $\delta$  is normally less than 0.3.

Sensitivity contours and gain circles on L M plane neatly relate gain, stability alignability and bandwidth at a glance

all h parameters in the above formulas can be replaced by the corresponding y parameters and 2g is replaced by Yg, then carry on all calculations.

The following examples arc shown for its design technique for c<1 and c>1

Reference: Transistors and active circuits by Linvill and Gibbons 1961 Mc Graw Hill Book co.

Part 2. Examples

a c<1 stable condition

use TI transistor 2N>43 in C E connection at 60mc ( $V_{\text{CB}}$ =5v  $I_{\text{C}}$ =5ma)

its h parameters are

 $h_{11} = 81.6 - j73.1 = 109.5 / -41.9$ 

 $h_{12}$ =.0592+ j.0661=.0887 / 48.1

 $h_{21} = -0.493 - j6.08 = 6.08 / -94.65$ 

 $h_{22} = (6.16 + j1.52)10^{-3} = 6.35 \cdot 10^{-3} / 13.85$ 

After calculation we get following data

c=.85  $\theta$ =-133.45 d=.557 (d= $\frac{\text{cg}}{2}$  at rad.=0)

 $P_{io}$ =51.5w 17.12 db,  $P_{oo}$ =1500 w, 31.77 db,  $G_r$ =43.75

 $G_{00}$ =29.1, 14.64 db  $K_g$ =1.31  $G_{max}$ =38.1, 15.82 db

If we use the maximum gain at the point circle,

Gmax=15.82 db at d=.557, then  $G_2=1.34 h_{22r}=8.25 10^{-3}$ 

 $B_2 = -0.4 \ h_{22r} = -2.46 \ 10^{-3} \ and \ Y_L = 8.25 \ 10^{-3} - 6.16 \ 10^{-3} = 2.09 \ 10^{-3}$ 

The sensitivity is too high  $\delta=2.35$ , therefore we use

 $\delta$ =.3 and we get Y<sub>L</sub> $\geq$ 16.4 10<sup>-3</sup> and G<sub>2</sub> $\geq$ h<sub>22r</sub>+|Y<sub>L</sub>| G<sub>2</sub> $\geq$ 3.66 h<sub>22r</sub>=22.56 10<sup>-3</sup> Then find a constant gain circle which is tangent to G<sub>L</sub>=3.66 h<sub>22r</sub> circle,

we get g=0.61 circle (G=17.7 12.5 db), its center is at  $-\frac{gc}{2}$ =-.26 and its

radius is 0.676, At the tangent point  $G_2$ =3.66  $h_{22r}$   $B_2$ =-0.4  $h_{22r}$  This gain circle g=0.61 (G=17.7, 12.5 db) is only 2.1 db less than  $G_{00}$  (14.64db), Then draw-3db constant gain circle i.e. 9.5 db (i.c. g=.306 G=8.9) constant gain

circle, its center is at  $-\frac{gc}{2} = -0.13$  and its radius is 0.844. This constant

gain circle g=.306 intersects the constant  $G_2$ =3.66  $h_{22r}$  circle at two points, we get  $B_{2e}$ = $-4h_{22r}$ ,  $B_{2b}$ =3.3  $h_{22r}$ , then  $\triangle B$ =7.3  $h_{22r}$ =45 10<sup>-8</sup>, the

total load capacitance is  $C_L = \frac{\triangle B}{2\triangle w}$ , Assuming a 3db bandwidth of 3mc for both input and output networks,  $c_L = 119.4$  pf,  $B_L = wc_L - \frac{1}{wL_2}$ 

 $^{\rm WL_2}$  =B<sub>2</sub>-h<sub>221</sub>, B<sub>L</sub>=-2.46  $10^{-3}$ -1.52  $10^{-3}$ = -3.98  $10^{-3}$  : L<sub>2</sub>=.054uh 2<sub>in</sub>=h<sub>11</sub>

 $-\frac{h_{12} h_{21}}{h_{22} + Y_L} = 66.35 - j54.7 = 86 / -39.5 \text{ r at } Y_L = 16.4 \cdot 10^{-3} \text{ If we use the input impedence overlay, we get } \frac{R_1}{|G_r|} = -.39 \frac{X_1}{|G_r|} = 0.35 \text{ at the tangent}$ 

point  $G_2=3.66$   $h_{22r}$   $B_2=-0.4$   $h_{22r}$  and  $-\theta=133.45$ ,  $2_{in}=h_{11}+R_1+jx_1=81.6$ 

$$\begin{split} -j73.1-17.1+j15.3=64.5-j57.8, & Y_{\rm in}=8.97\ 10^{-3}+j7.4\ 10^{-3}=11.63\ 10^{-3}\ /\ 39.5\\ Y_{\rm g}=8.97\ 10^{-3}-j7.4\ 10^{-3}, & Y_{\rm ont}=h_{22}-\frac{h_{12}}{h_{11}+2_{\rm g}}=3.36\ 10^{-3}+j3.82\ 10^{-3}\ Y_{\rm ont}=5.1\ 10^{-3}\\ /\ 48.7, & C_{\rm out}=\frac{3.82\ 10^{-3}}{2\pi.\ 610^3}=10.4 {\rm pf}. & (transistor\ output\ capacitance}) & Then calculate the parallel equivalent of the conpling condenser $c_{2a}$ which is in series with $R_2$ (50r) as shown in Fig. 10. $c_{2a}=\frac{1}{W\theta_2}\ R_2$ $\theta_L=\sqrt{\frac{1}{G_L}}-1$ $G_L=|Y_L|=16.4\ 10^{-3}\ \theta_L=0.47$ (to get 3db bandwidth) $c_{2a}=112.8$ pf (use 110 pf) $c_{2a}'=c_{2a}\left(\frac{1}{1+\frac{1}{\theta_L}^2}\right)=19.9$ pf $\therefore$ $c_2$ tank=119.4-10.4-19.9=89.1$ pf (variable one) The transistor input capacitance is $c_{\rm in}=\frac{7.4\ 10^{-3}}{2\pi.\ 610^7}=19.6$ pf The total source capacitance is $c_g=\frac{2\theta_s\ R_e\ (Y_{\rm in})}{W}=143$ pf with $\theta_s=3$, $c_{1a}=\frac{1}{W\ \theta_{\rm in}\ R_1}$ $\theta_{\rm in}=\sqrt{\frac{1}{R_e\ (Y_{\rm in})\ R_1}}-1=1.11$ at $R_1=500$ $c_{1a}=47.8$ pf (use 47 pf) $c_{1a}'=c_{1a}$ $\frac{1}{1+\frac{1}{\theta_{\rm in}^2}}=25.9$ pf $c_1$ tank=143-19.6-25.9=97.5$ pf $c_2$ tank=143-19.6-25.9=97.5$ pf $c_1$ tank=143-19.6-25.9=97.5$ pf $c_2$ tank=143-19.6-25.9=97.5$ pf $c_2$ tank=143-19.6-25.9=97.5$ pf $c_2$ tank=143-19.6-25.9=97.5$ pf $c_3$ tank=143-19.6-25.9=97.5$ pf $c_4$ tank$$

(variable one)  $L_1 = \frac{1}{w^2 c_\alpha} = .0492uh$ 

The process is shown in the figure 10 and the circuit diagram is shown in Fig. 11

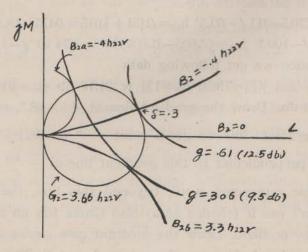
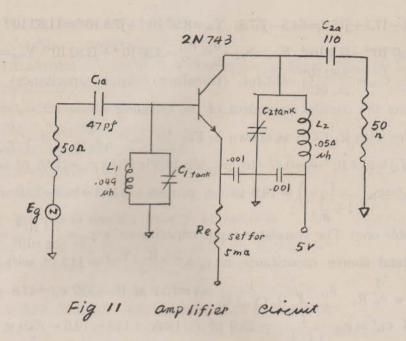


Fig. 10 Linvill's chart



## b. Example 2 c>1 potentially unstable condition

The IF transistors uses to have c>1, since c decreases with increasing frequency, If we use one series of transistors for the tuner set we get this problem.

use G. E. silicon transistor IN 3855 at 10.7mc (FM, IF, at  $V_{\text{ce}}{=}10v$ ,  $I_{\text{c}}{=}3\text{ma}$ ) its h parameters are

 $\begin{array}{lll} h_{11}\!=\!154.2\!-\!j270.5\!=\!311\,/\!-60.3 & h_{12}\!=\!.0451\!+\!j.015\!=\!.0475\!/\ 18.4 & h_{21}\!=\!-4.24\!-\!j23.85 & =\!24.2\,/\!-100.1 & h_{22}\!=\!(3.605\!-\!j1.007)10^{-8}\!=\!3.74\,10^{-3}/\!-15.6 \end{array}$ 

After calculation we get following data

c=1,218  $\theta$ =-98.3 |G<sub>r</sub>|=159.6 p<sub>io</sub>=131 w 21.16 db p<sub>oo</sub>=40600 w 46.07 db G<sub>oo</sub>=310, 24.9 db. Draw the gradient line at  $\theta$ =-98.3, on the negative side of this gradient line we get a point  $-\frac{1}{c}$ =-.821

draw a line perpendicular to this gradient line at  $-\frac{1}{C}$ 

point this line represents  $p_i=0$ , beyoned this line, the region is for  $p_i<0$ , we can't use it (shaded area) also Gmax has no meaning as the transistor may oscillate. Draw the constant gain circles as in the usual way, all the gain circles pass the points A and B. The g=1 (24.9 db) circle passes the origin and A. B points

Assume  $\delta$ =.3 we get  $|Y_L| \ge 12.36 \, 10^{-3}$  and  $G_2 \ge 3.47 \, h_{22r}$  use  $G_2 = 3.5 \, h_{22r}$  circle, To find the gain circle which tangents this  $G_2$ =3.5  $h_{22r}$  circle, we get g=.821 (-.86 db) G=255 24.07 db, its center is at  $-\frac{\text{cg}}{2} = -.5$  its radius is 0.656, The tangent point is at  $G_2 = 3.5 \, h_{22r} = 12.62 \, 10^{-3} \, B_2 = -1.1 \, h_{22r} = -3.9 \, 10^{-3}$ , Then draw g=.412, 21.07 db G=128 circle with its center

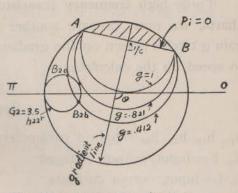


Fig. 12 Gain circle Diagrom

at .25 and radius equal to 0.807 The intersecting points of  $G_2=3.5\ h_{22r}$  and 21.07 db gain circle are at  $B_{2c}=-4.2\ h_{22r}$ ,  $B_{2b}=2.2\ h_{22r}$  .  $\triangle B=6.4\ h_{22r}=0.96\ 10^{-3}$ ,  $c_L=\frac{\triangle B}{2\triangle w}=306$  pf with bandwidth 250 kc (FM, IF band width),  $B_L=wc_L-\frac{1}{wL_2}=B_2-h_{221}=-1.1\ h_{22}-h_{221}=-2.953\ 10^{-3}$  .  $L_2=.634$   $\mu h\ 2_{in}=139.34-j200=244\ /-55.1$  with  $Y_L=12.4\ 10^{-3}\ Y_{in}=4.110^{-3}\ /55.1$   $c_{in}=\frac{3.36\ 10^{-3}}{67.2\ 10^6}=50.1$  pf  $G_{in}=2.35\ 10^{-3}\ R_{in}=426Q\ Y_g=(2.35-j3.364)\ 10^{-3}\ Y_{out}=(2.19+j2.54)\ 10^{-3}=2.36\ 10^{-3}\ /49.2$  with  $Y_g=4.1\ 10^{-3}\ /-55.1$  . . cont =37.8 pf  $(\frac{2.54\ 10^{-3}}{67.2\ 10^6}=37.8$  pf  $C_{2b}=306-37.8=268.2$  pf (tank)  $G_{out}=2.19\ 10^{-3}\ R_{out}=456s_L\ c_1\ tank=268.2$  pf If we use the input impedance overlay we get  $\frac{R_1}{|G_r|}=-.185\ and \frac{X_1}{|G_r|}=0.49$  .  $R_1=-29.5\ X_1=78$  then  $2_{in}=154.2-j270.5$   $-29.5+j78=124.7-j192.5=230\ /-57.1$  when we design the IF stage of FM receiver, we select high  $h_{11r}$  transistor, because when the freguency swings to lower side, the load is inductive which by Miller effect turns out more negative input resistance and causes oscillation, If  $h_{11r}$  is high enoguh, we get position input resistance the IF stage is then stable,

Finally we apply sterns stabilety formula to check the stability of the stages  $(y_{11r}+G_g)$   $(y_{22r}+G_L)=k(\frac{u+v}{2})$  If k>1 the system is stable if k<1 the system is unstable  $G_g$  is the source conductance,  $G_L$  is the load conductance  $u=|y_{12}|$   $y_{21}|$   $v=R_g$   $(y_{12}|$   $y_{21})$   $y_{11r}$ ,  $y_{22r}$  are real parts of  $y_{11}$  and  $y_{22}$ 

To do high frequency transistor amplifier design by using Linvill's charts, we must prepare another two transparent overlays of constant gain g circles drawn on the gradient line and constant sensitivity  $\delta$  chart to speed up the calculation

## Symbols

 $h_{11}$ ,  $h_{12}$ ,  $h_{21}$   $h_{22}$ ="hybrid" parameters

 $E_1$ ,  $E_2$ =input, output voltages

 $I_1$ ,  $I_2$ =input, output currents

p<sub>i</sub>=Input power p<sub>io</sub>=Input power at L=1, M=0 point

 $p_0$ =output power  $p_{00}$ =power output at L=1 M=0 point

 $G_r$ =Gradient  $\theta$ =angle of gradient line

m, m'=slope of a line

c=Linvill's stability factor

R<sub>e</sub>=Real part of Im=Imaginary part of

 $h_{11r},\ h_{12r},\ h_{21r},\ h_{22r}, = real\ part\ of\ h_{11},\ h_{12},\ h_{21},\ h_{22}$ 

 $G_{\infty}$ =power gain at L=1, M=0

G=power gain, Gopt=max, power gain.

k<sub>E</sub>=power ratio

Y<sub>L</sub>=load admittance, G<sub>L</sub>=load conductance

B<sub>L</sub>=load susceptance

 $\delta$ =sensitivity factor